

75 Naxos Way, Keysborough 3173 Victoria Australia P: +61 3 8770 6555 E: support@eqss.com.au

## Genie Smartlink Installation Manual

**REV 2.4** 

28/11/2023

Model6253 OverWatch™ Installation Manual

Document # DO001205

## EQSS Model6253 – OverWatch™ Genie Smartlink Series



<sup>\*\*</sup> Failure to follow this installation manual will void warranty \*\*





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DOCUMENT ABSTRACT: This Installation Manual details the man scissor lift equipped with a Smartlink ope		ns for installing the Model6253 OverWatch on a Gen	ie
PRODUCT NAME: Model6253 OverWatch Operator Detect	ion System		
REFERENCE DOCUMENTS: DO001195 Model6253 OverWatch User	Manual		
CURRENT DOCUMENT REVISION: 2.4			
<ul> <li>1.2 Update of instructions of so</li> <li>2.0 Update of instructions to we</li> <li>2.1 Modified Ø3.2mm through</li> </ul>	mages and inclusion of harness s ard and new sensor bracket	ecuring connections via P-clip 01928	



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### **Important Information**

Information contained in this publication regarding this device's applications and the like, is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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This is a class A product certified to AS/NZS CISPR 22:2006. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.



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## **Preparation**

## **Required Tools**

The OverWatch has been designed to be fitted using basic workshop tools. Shown below is a list of tools required to complete the installation.

Item	Tool / Description
1	Electric Drill
2	Centre Punch
3	Hammer
4	Side Cutters
5	Drill 5.0mm
6	Drill 6.0mm
7	Sockets & Spanners
8	Needle Nose Pliers
9	Screwdrivers
10	Hot glue and hot glue gun

### **Installation Time**

The suggested time required to install the OverWatch is detailed below.

Task		Estimated Time (Minutes)
Open the operator control box		5
Drilling of all mounting holes for the various components		10
Mechanical assembly		10
Electrical assembly		30
Post installation system tests		10
Close the operator control box		5
	Total	70



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## **Installation Instructions**

## **Operator Sensor**

		Diagram
1.	Remove the Joystick controller from the metal housing.	STOP STOP
2.	Drill two 6mm holes to mount the operator sensor in the position shown in the diagram.  Hole #1: 25mm from the top horizontal edge and 34mm from the left vertical edge.  Hole #2: 42mm vertically down from the centre of the hole 1 and 45mm horizontal. The distance between the two holes is 61mm.  Note: The sensor should be mounted at an angle	Asmm Asmm



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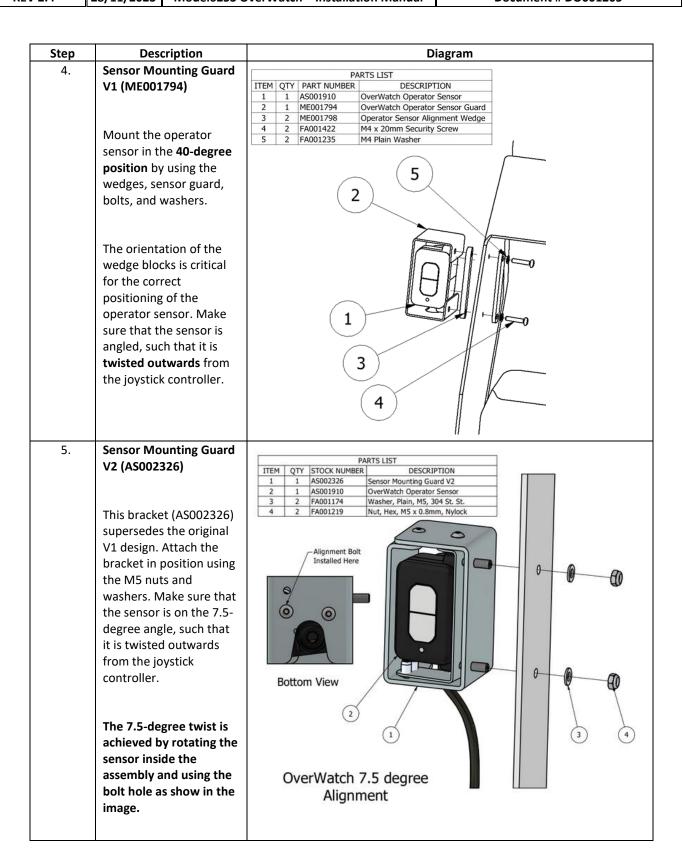
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Step	Description	Diagram
6.	Route the operator sensor cable as shown in the diagram. Use P-Clips to secure the cable to the metal enclosure.	APPORTS ACIDS  APPORT



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### **Control Module**

Step	Description	Diagram
1.	Remove the bottom plastic cover from the joystick to expose the inside wiring and electronics.	
2.	Remove the buzzer, E-Stop, and the Genie circuit board.	



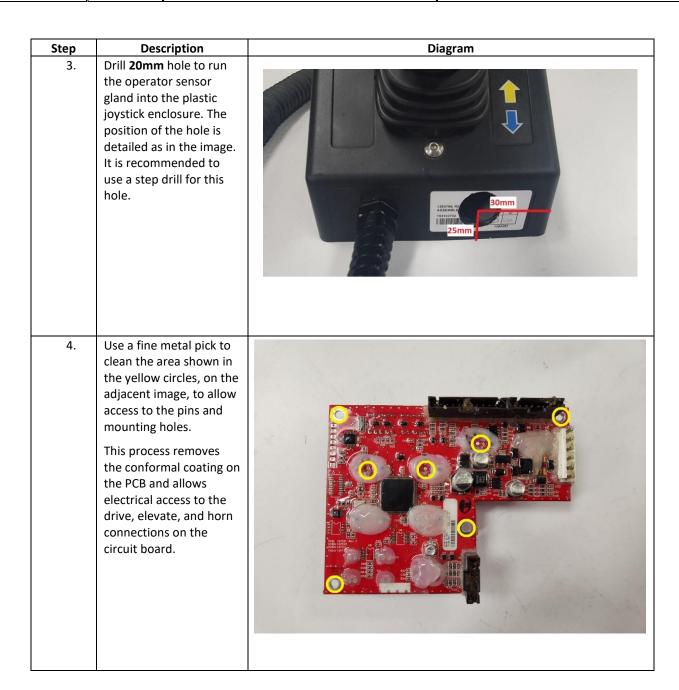
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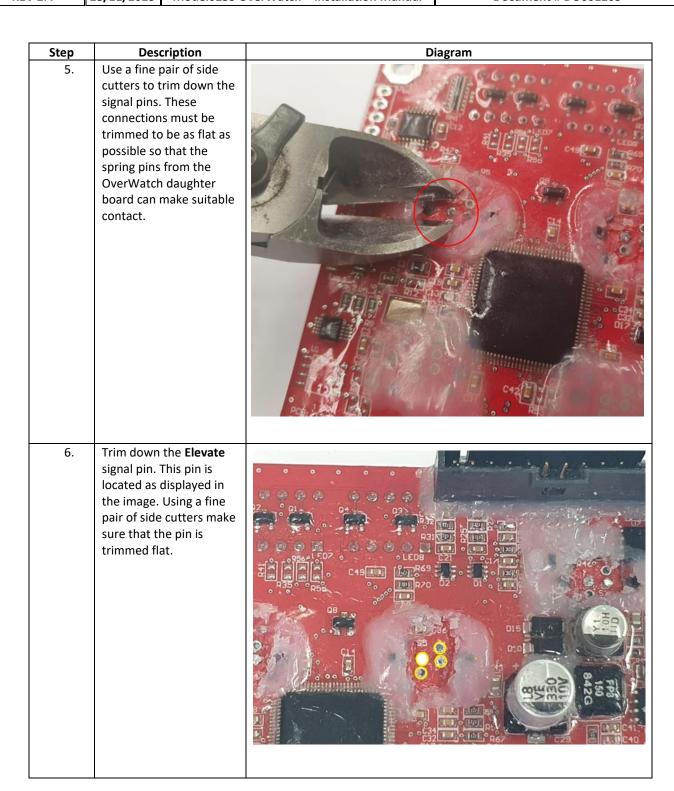
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Step	Description	Diagram
7.	Trim down the <b>Drive</b> signal pin. This pin is located as displayed in the adjacent image. Using a fine pair of side cutters make sure that the pin is trimmed flat.	
8.	Trim down the two Horn signal pins. These pins are located as displayed in the adjacent image. Using a fine pair of side cutters make sure that the pins are trimmed flat.	DIST DIST PROPERTY OF THE PROP



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Step	Description	Diagram
9.	Wiring connections are made with the OverWatch harness AS001928.  Supplied with the harness is the following hardware:  4 x 6.4mm spacers  4 x G4x19mm Bolts  These hardware components are critical and must be used to space the daughter board above the Genie circuit board	Joystick Connection  Power Connection
10.	Mount the Overwatch daughter board on top of the Genie circuit board by using the provided screws and spacers in the kit.  Make sure that the board is sitting in the correct position and the spring pins are contacting the Genie circuit board signal points.	NO MONTO OR ROGGET FOR EXAMELLE TOO NO MONTO OR ROGGET FOR TO STATE TO STAT



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## Step Description Diagram 11. Joystick connection: Install the Overwatch connectors in between the joystick and the Genie circuit board connector. Visually check that all pins from original joystick connector have a corresponding cable on the Overwatch harness. Reconnect the other connectors, which were disconnected in step 2. 12. **Power Connection:** At the back of the E-Stop, install the OverWatch red power cable to terminal 2 of the E-Stop. **Note:** This cable might need to be changed to terminal 1 if the Overwatch is powered with the E-Stop pushed in.



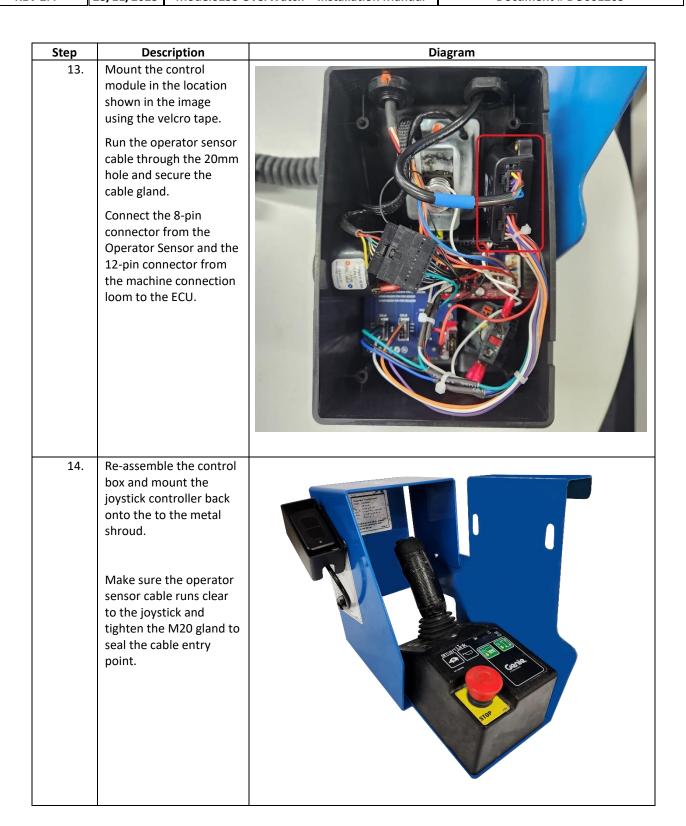
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## **Post Installation Configuration**

### Overview

After the system has been installed it must be configured with the parameters to suit the machine. Follow the instructions below to configure the OverWatch.

### Minimum system requirements

Any smart phone, tablet or laptop that meets the following requirements:

- The device can connect to a Wi-Fi access point
- The device has an up to date web browser installed. Firefox, Chrome or Safari are recommended.

### Wi-Fi Connection & Web Page Access

To enable the Wi-Fi connection on the OverWatch to complete the configuration follow the steps below.

- 1. Power down the platform control box with the ESTOP
- 2. Wait 5 seconds
- 3. Power up the platform control box with the ESTOP
- 4. While standing in front of the operator sensor, switch on the OverWatch
- 5. As the welcome chime starts to play, cover the sensor. The LED will flash white then black to acknowledge.
- 6. Remove your hand from the sensor. The LED will flash white then black to acknowledge.
- 7. After covering then uncovering the sensor this way 2 more times, "Wi-Fi On" will be announced
- 8. On your Wi-Fi enabled device (laptop, tablet, smartphone, etc), show the available wireless networks
- 9. Select the wireless network (starts with "overwatch") to connect to the OverWatch
- 10. When prompted, enter the password 12345678
- 11. Open your preferred web browser (Chrome, Firefox, Safari)
- 12. Enter the following into the address bar <a href="http://192.168.4.1">http://192.168.4.1</a> to open the OverWatch main page



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### **Machine Model Selection**

Follow the instructions below to configure the OverWatch.

- 1. Select the Setup option
- 2. If there is a password field at the bottom of the page, follow the instructions in Change Model Configuration to obtain the password and enter the password field
- 3. Select the EWP Model from the drop-down list and click Set
- 4. Click on Proceed to test to begin the installation test





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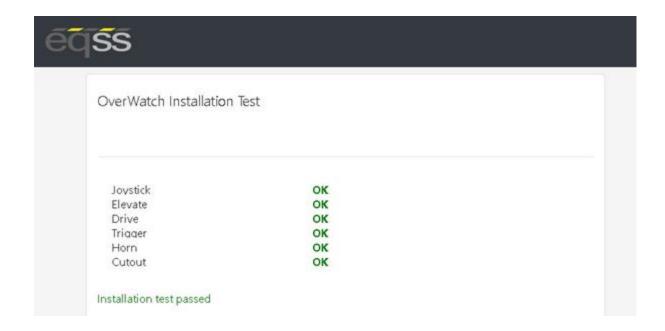
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### **Installation Test**

After the model configuration has been set or updated an Installation Test must be performed. This will ensure the installation has been correctly performed and the OverWatch is functioning correctly. Follow the instructions on the web page to complete the Installation Test.





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## **Change Model Configuration**

To reconfigure the OverWatch for a different model requires an authorisation password. The authorisation password is generated from the EQSS website. The EQSS website requires a login username and password, contact EQSS for these details.

Follow the instructions below to obtain an authorisation password. It is important to note that each ECU has a unique serial number and a unique password.

- 1. Open your web and enter the following into the address bar <a href="http://www.eqss.com.au/overwatch">http://www.eqss.com.au/overwatch</a> to open the Login page
- 2. Enter your username and password
- 3. Enter the EUC serial number which is shown on the setup page or on the ECU serial number sticker, also enter the owner and model details of the EWP and then click Generate Hash
- 4. The generated Hash code or password can be used to change the model configuration.





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## **System Settings**

### **Default Parameters**

The OverWatch is configurated with the following default parameters.

Setting Name	Description	Default
max_safe_velocity	This is the velocity threshold for the cutout in cm/s for drive mode.	95
max_safe_displacement	This is the maximum permitted distance in cm the operator may be away from the calibration position in drive mode.	50
max_safe_velocity_elevate	This is the velocity threshold for the cutout in cm/s for elevate mode.	75
max_safe_displacement_elevate	This is the maximum permitted distance in cm the operator may be away from the calibration position in elevate mode.	50
fwddispadj	The proportion of the calibration distance toward the sensor permitted to the operator.	0.7
fwdveloadj	The coefficient to apply to the maximum allowable velocity when the movement of the operator is toward the sensor.	1.0
zone_obstruction	If the lidar sensor reading is below this, the lidar is considered to be obstructed (with paint or thick coat of dust) and the system is cutout until the obstruction is cleared.	5
zone_minimum	The minimum calibration distance. If the operator is closer to the sensor than this "operator zone" will be announced.	17
zone_maximum	The maximum calibration distance. If the operator is further from the sensor than this "operator zone" will be announced.	120
adc_elevate_threshold	Threshold value for the elevate ADC input.	100
adc_drive_threshold	Threshold value for the drive ADC input.	100
adc_trigger_threshold	Threshold value for the trigger ADC input.	100
adc_joystick_fwd_threshold	Forward threshold value for the joystick ADC input.	1525
adc_joystick_bwd_threshold	Backward threshold value for the joystick ADC input.	1375
throttle_time	Period after the trigger is pressed (ms) during which initial velocity reading is computed.	500
driving_state_timeout	Mode selection switch timeout (ms)	7000





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## **Polarity and Input Style**

The table below describes each setting

Setting Name	Description	Default
joystick_drive_forward	Direction of joystick to move machine forward	forward
joystick_elevate_upward	Direction of joystick to move machine upwards	forward
elevate_polarity	Direction of signal logic	low
drive_polarity	Direction of signal logic	low
trigger_polarity	Direction of signal logic	low
joystick_polarity	Direction of signal logic	high
driving_state_input	Direct or timer based	timer



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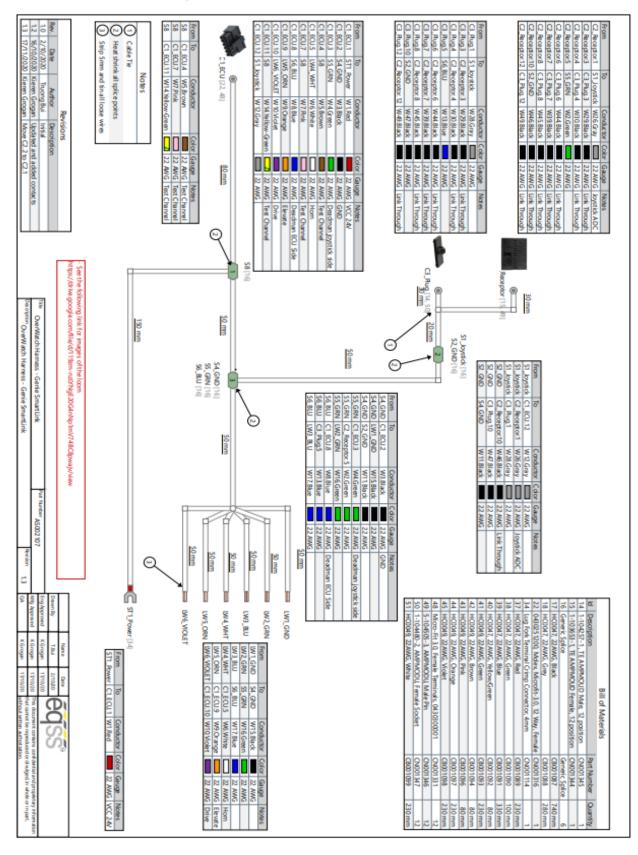
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## **Harness Drawing AS001928**





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## **Replacement Parts**

Replacement parts for this OverWatch kit are available from EQSS, for all inquiries please email <a href="mailto:sales@eqss.com.au">sales@eqss.com.au</a>
Shown below are the part numbers for the major components included in this model specific kit.

Part Number	Description
AS001941	OverWatch - Complete kit for Genie Smartlink Series Control Box
AS001910	OverWatch - Operator Sensor with M20 gland
AS001916	OverWatch – Electronic Control Unit (ECU)
AS001928	OverWatch - Genie Smartlink Harness
AS002326	OverWatch - Sensor Guard V2