

75 Naxos Way, Keysborough 3173 Victoria Australia P: +61 3 8770 6555 E: support@eqss.com.au

### Haulotte Compact Installation Manual

**REV 1.2** 

30/11/2023

**Model6253 OverWatch™ Installation Manual** 

Document # DO001252

# EQSS Model6253 – OverWatch™ Haulotte Compact Slab Scissor



\*\* Failure to follow this installation manual will void warranty \*\*





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| 2001145117 42072407                          |   |                                 |
| DOCUMENT ABSTRACT:                           |   |                                 |
| This Installation Manual details the manufac | cturer's installation instructions for installing | ng the Model6253 OverWatch on a |
| Haulotte Compact Slab Scissor lift.          |   |                                 |
| PRODUCT NAME:                                |   |                                 |
| Model6253 OverWatch™ Operator Detectio       | n System  |                                 |
|  |   |                                 |
| REFERENCE DOCUMENTS:                         |   |                                 |
| DO0001195 Model6253 OverWatch™ User l        | Manual  |                                 |
|  |   |                                 |
| CURRENT DOCUMENT REVISION:                   |   |                                 |
| 1.2  |   |                                 |
|  |   |                                 |
| REVISION INFORMATION:                        |   |                                 |
|  |   |                                 |
|  | nstallation on a Haulotte Compact Slab Scis       |                                 |
|  | V2 and update of model configuration ins          | tructions.                      |
| 1.2 Inclusion of machine harness so          | chematic.   |                                 |
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### **Important Information**

Information contained in this publication regarding this device's applications and the like, is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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### **Preparation**

### **Required Tools**

The OverWatch has been designed to be fitted using basic workshop tools. Shown below is a list of tools required to complete the installation

| Item | Tool / Description         |
|------|----------------------------|
| 1    | Electric Drill             |
| 2    | Centre punch               |
| 3    | Hammer                     |
| 4    | Side Cutters               |
| 5    | Drill 5.2mm                |
| 6    | Drill 6.0mm                |
| 7    | Metric sockets or spanners |
| 8    | Needle nose pliers         |
| 9    | Screw drivers              |

### **Installation Time**

The suggested time required to install the OverWatch is as detailed below

| Task  | Estimated Time (Minutes) |
|---|--------------------------|
| Open the operator control box                             | 1                        |
| Drilling of all mounting holes for the various components | 13                       |
| Mechanical assembly                                       | 10                       |
| Electrical assembly                                       | 10                       |
| Post installation system tests                            | 10                       |
| Close the operator control box                            | 1                        |
| Т   | otal 45                  |



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### **Installation Instructions**

### **Operator Sensor**

| Step | Description  | Diagram          |
|------|--|------------------|
| 1.   | The platform control box has two main components:  1. Joystick shroud  2. Control box  |                  |
| 2.   | On the joystick shroud drill two 6.00mm holes 61.00mm apart in the locations shown in the image. The location of these holes is critical for the operator sensor to be mounted at an angle of 30 degrees from the vertical  Note: The operator sensor must be mounted at an angle of 30 degrees from the vertical, this is critical for correct system operation | 15<br>32<br>2xφ5 |



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3. Remove the bottom cover from control box. And drill the necessary holes as per the adjacent drawing.

2 x 5.00mm holes spaced 65.00mm apart (ECU Module)

2 x 5.00mm holes, spaced 55.00mm apart (Cable Gland Guard)

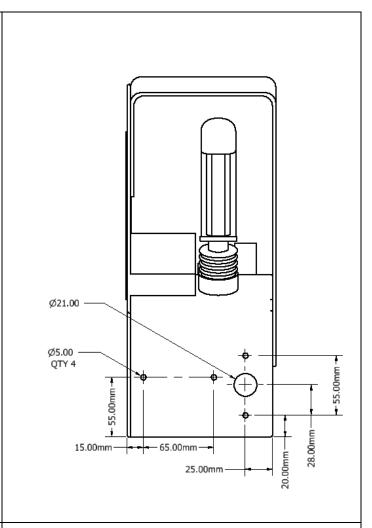
**1 x 21.00mm** hole (M20 Cable Gland)

#### \*\*Warning\*\*

Keep the control box standing upright during drilling to avoid swarf going in the middle of wiring and electronics.

#### \*\*Warning\*\*

Clean swarf before going further in the installation.

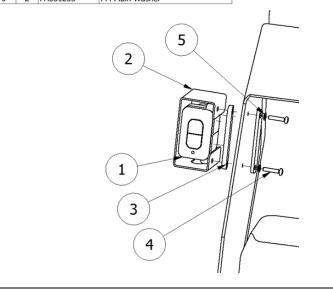


# 4. Sensor Mounting Guard V1 (ME001794)

Mount the operator sensor in the **30-degree position** by using the wedges, sensor guard, bolts, and washers.

The orientation of the wedge blocks is critical for the correct positioning of the operator sensor. Make sure that the sensor is angled, such that it is **twisted outwards** from the joystick controller. Mount the sensor in position using the positioning wedges, sensor guard, M4 washers, and bolts.

|      |     | P/          | ARTS LIST                       |
|------|-----|-------------|---------------------------------|
| ITEM | QTY | PART NUMBER | DESCRIPTION                     |
| 1    | 1   | AS001910    | OverWatch Operator Sensor       |
| 2    | 1   | ME001794    | OverWatch Operator Sensor Guard |
| 3    | 2   | ME001798    | Operator Sensor Alignment Wedge |
| 4    | 2   | FA001422    | M4 x 20mm Security Screw        |
| 5    | 2   | FA001235    | M4 Plain Washer                 |





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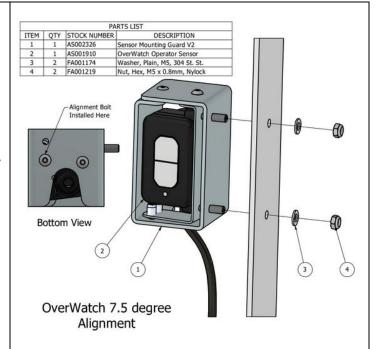
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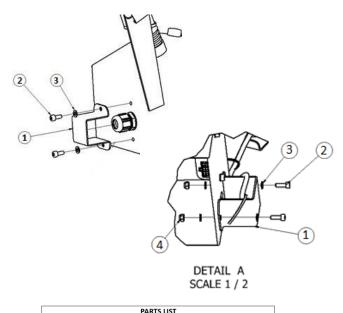
# 5. Sensor Mounting Guard V2 (AS002326)

This guard (AS002326) supersedes the original V1 design. Attach the guard in position using the M5 nuts and washers. Make sure that the sensor is on the 7.5-degree angle, such that it is twisted outwards from the joystick controller.

The 7.5-degree twist is achieved by rotating the sensor inside the assembly and using the bolt hole as show in the image.



6. Install the cable gland and cable gland guard in the pre-drilled holes.



|      | PARTS LIST |             |                             |
|------|------------|-------------|-----------------------------|
| ITEM | QTY        | PART NUMBER | DESCRIPTION                 |
| 1    | 1          | ME001793    | Cable Gland Guard           |
| 2    | 2          | FA001211    | M4 x 12mm Socket Head Screw |
| 3    | 4          | FA001235    | M4 Plain Washer             |
| 4    | 2          | FA001223    | M4 Nylock Nut               |



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### **Control Module**

| Step | Description  | Diagram  |  |
|------|--|--|--|
| 1.   | Using the M4 bolts and washers, mount the ECU inside the joystick enclosure. Ensure connectors are facing downwards. |  |  |
|      |  | PARTS LIST  ITEM QTY STOCK NUMBER DESCRIPTION  |  |
|      |  | 1         4         FA001235         Washer, Plain, M4, 304 St. St.           2         1         AS001916         OverWatch™ ECU Module |  |
|      |  | 3 2 FA001211 Socket Head Cap Screw, M4 x 0.7 x 12mm  |  |
| 2.   | Wiring connections are made with the AS001974 harness.   | Trigger and Operation Mode Connection  Power  Horn   |  |



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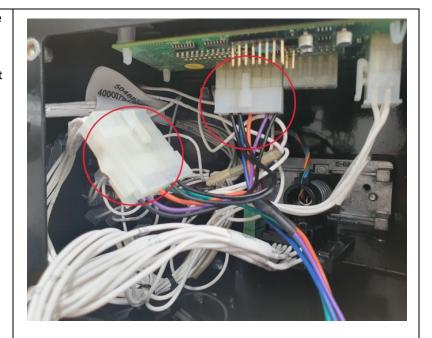
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# 3. Trigger, drive and elevate connection:

Disconnect the 7-pin connector from the circuit board and Install the OverWatch harness connector in series.



#### 4. **Joystick Connection:**

Disconnect the 5-pin connector from the circuit board and Install the OverWatch harness connector in series.





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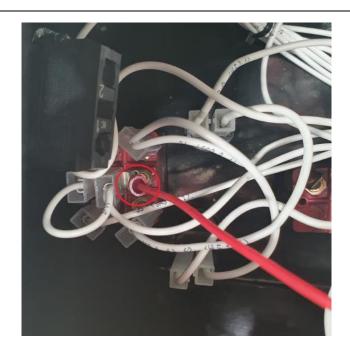
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#### 5. **Power Connection:**

At the back of the drive/elevate selection switch locate wire **ID 11**.

install the OverWatch red power wire using the piggy back spade connector

Note: Check that the connection is tight, use needle nose pliers to squeeze the connection if necessary



#### 6. **Horn Connection:**

At the back of the horn switch locate wire **ID 36**.

install the OverWatch white horn wire using the piggy back spade connector

Note: Check that the connection is tight, use needle nose pliers to squeeze the connection if necessary





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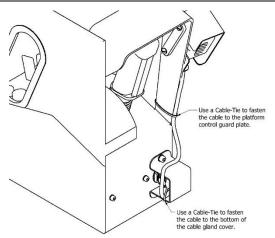
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7. Connect the 8-pin connector from the operator sensor, and the 12-pin connector from the harness into the ECU. Install the cover back onto the bottom of the joystick enclosure.



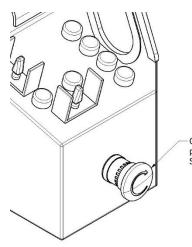
8. Route the operator sensor cable as shown in the image and secure the cable using cable ties.



9. After installation, power the machine for platform controls and press the emergency stop.

While the emergency stop is active the OverWatch should be switched off.

If the OverWatch remains powered, check that the correct side of E-Stop has been used for the OverWatch power.



OverWatch™ should not be powered when Emergency Stop has been activated.



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### **Post Installation Configuration**

#### **Overview**

After the system has been installed it must be configured with the parameters to suit the machine. Follow the instructions below to configure the OverWatch.

### Minimum system requirements

Any smart phone, tablet or laptop that meets the following requirements:

- The device can connect to a Wi-Fi access point
- The device has an up to date web browser installed. Firefox, Chrome or Safari are recommended.

### Wi-Fi Connection & Web Page Access

To enable the Wi-Fi connection on the OverWatch to complete the configuration follow the steps below.

- 1. Power down the platform control box with the ESTOP
- 2. Wait 5 seconds
- 3. Power up the platform control box with the ESTOP
- 4. While standing in front of the operator sensor, switch on the OverWatch
- 5. As the welcome chime starts to play, cover the sensor. The LED will flash white then black to acknowledge.
- 6. Remove your hand from the sensor. The LED will flash white then black to acknowledge.
- 7. After covering then uncovering the sensor this way 2 more times, "Wi-Fi On" will be announced
- 8. On your Wi-Fi enabled device (laptop, tablet, smartphone, etc), show the available wireless networks
- 9. Select the wireless network (starts with "overwatch") to connect to the OverWatch
- 10. When prompted, enter the password 12345678
- 11. Open your preferred web browser (Chrome, Firefox, Safari)

Enter the following into the address bar <a href="http://192.168.4.1">http://192.168.4.1</a> to open the OverWatch main page



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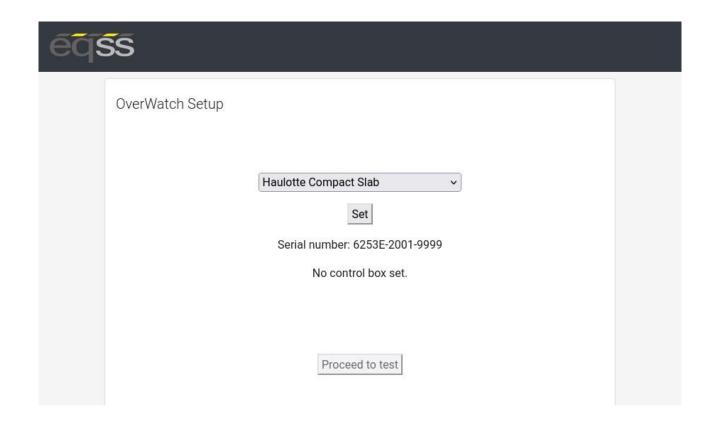
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#### **Machine Model Selection**

Follow the instructions below to configure the OverWatch.

- 1. Select the Setup option
- 2. If there is a password field at the bottom of the page, follow the instructions in Change Model Configuration to obtain the password and enter the password field
- 3. Select the EWP Model from the drop-down list and click Set
- 4. Click on Proceed to test to begin the installation test





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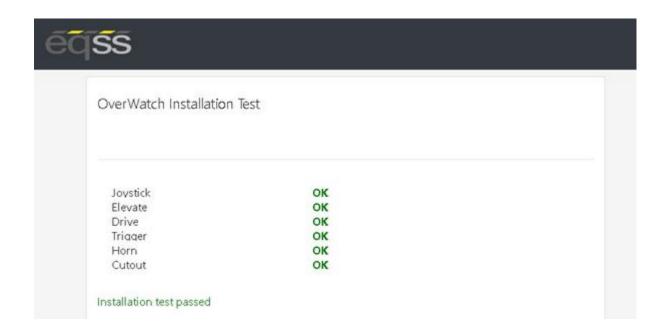
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#### **Installation Test**

After the model configuration has been set or updated an Installation Test must be performed. This will ensure the installation has been correctly performed and the OverWatch is functioning correctly. Follow the instructions on the web page to complete the Installation Test.







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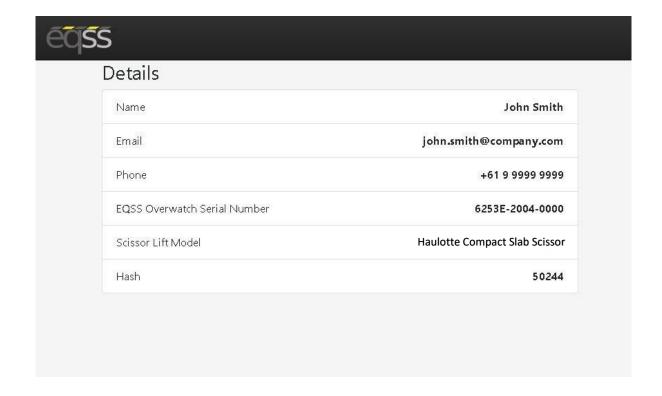
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### **Change Model Configuration**

To reconfigure the OverWatch for a different model requires an authorisation password. The authorisation password is generated from the EQSS website. The EQSS website requires a login username and password, contact EQSS for these details.

Follow the instructions below to obtain an authorisation password. It is important to note that each ECU has a unique serial number and a unique password.

- 1. Open your web browser and enter the following into the address bar <a href="http://www.eqss.com.au/overwatch">http://www.eqss.com.au/overwatch</a> to open the Login page
- 2. Enter your username and password
- 3. Enter the EUC serial number which is shown on the setup page or on the ECU serial number sticker, also enter the owner and model details of the EWP and then click Generate Hash
- 4. The generated Hash code or password can be used to change the model configuration.





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# **System Settings**

### **Default Parameters**

The OverWatch is configured with the following default parameters.

| Setting Name                  | Description   | Default |
|-------------------------------|---|---------|
| max_safe_velocity             | This is the velocity threshold for the cutout in cm/s for drive mode.   | 95      |
| max_safe_displacement         | This is the maximum permitted distance in cm the operator may be away from the calibration position in drive mode.  | 50      |
| max_safe_velocity_elevate     | This is the velocity threshold for the cutout in cm/s for elevate mode.   | 75      |
| max_safe_displacement_elevate | This is the maximum permitted distance in cm the operator may be away from the calibration position in elevate mode.  | 50      |
| fwddispadj                    | The proportion of the calibration distance toward the sensor permitted to the operator.   | 0.7     |
| fwdveloadj                    | The coefficient to apply to the maximum allowable velocity when the movement of the operator is toward the sensor.  | 1.0     |
| zone_obstruction              | If the lidar sensor reading is below this, the lidar is considered to be obstructed (with paint or thick coat of dust) and the system is cutout until the obstruction is cleared. | 5       |
| zone_minimum                  | The minimum calibration distance. If the operator is closer to the sensor than this "operator zone" will be announced.  | 17      |
| zone_maximum                  | The maximum calibration distance. If the operator is further from the sensor than this "operator zone" will be announced.   | 120     |
| adc_elevate_threshold         | Threshold value for the elevate ADC input.  | 2200    |
| adc_drive_threshold           | Threshold value for the drive ADC input.  | 2200    |
| adc_trigger_threshold         | Threshold value for the trigger ADC input.  | 2000    |
| adc_joystick_fwd_threshold    | Forward threshold value for the joystick ADC input.   | 1600    |
| adc_joystick_bwd_threshold    | Backward threshold value for the joystick ADC input.  | 1400    |
| throttle_time                 | Period after the trigger is pressed (ms) during which initial velocity reading is computed.   | 500     |
| driving_state_timeout         | Mode selection switch timeout (ms)  | 7000    |





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### **Polarity and Input Style**

The table below describes each setting

| Setting Name            | Description                                   | Default |
|-------------------------|---|---------|
| joystick_drive_forward  | Direction of joystick to move machine forward | forward |
| joystick_elevate_upward | Direction of joystick to move machine upwards | forward |
| elevate_polarity        | Direction of signal logic                     | high    |
| drive_polarity          | Direction of signal logic                     | high    |
| trigger_polarity        | Direction of signal logic                     | high    |
| joystick_polarity       | Direction of signal logic                     | high    |
| driving_state_input     | Direct or timer based                         | direct  |



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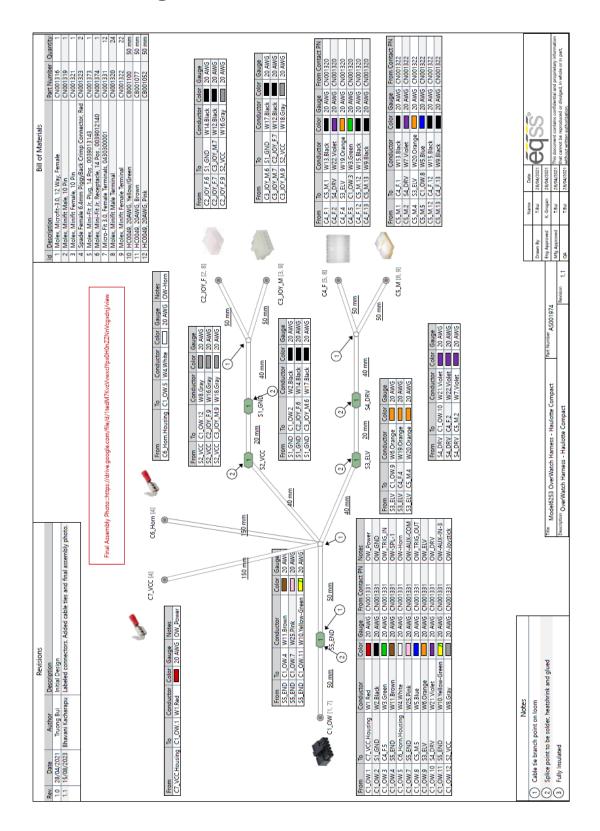
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### **Harness Drawing AS001974**







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### **Replacement Parts**

Replacement parts for this OverWatch kit are available from EQSS, please email <a href="mailto:sales@eqss.com.au">sales@eqss.com.au</a>

Shown below are the part numbers for the major components included in this model specific kit.

| Part Number | Description                                |
|-------------|--|
| AS001973    | OverWatch - Complete kit Haulotte Compact  |
| AS001910    | OverWatch - Operator Sensor with M20 gland |
| AS001916    | OverWatch - Electronic Control Unit (ECU)  |
| AS001974    | OverWatch - Haulotte Compact Harness       |
| AS002326    | OverWatch - Sensor Guard V2                |

