

75 Naxos Way, Keysborough 3173 Victoria Australia P: +61 3 8770 6555 E: support@eqss.com.au

Skyjack Large RT Series Installation Manual

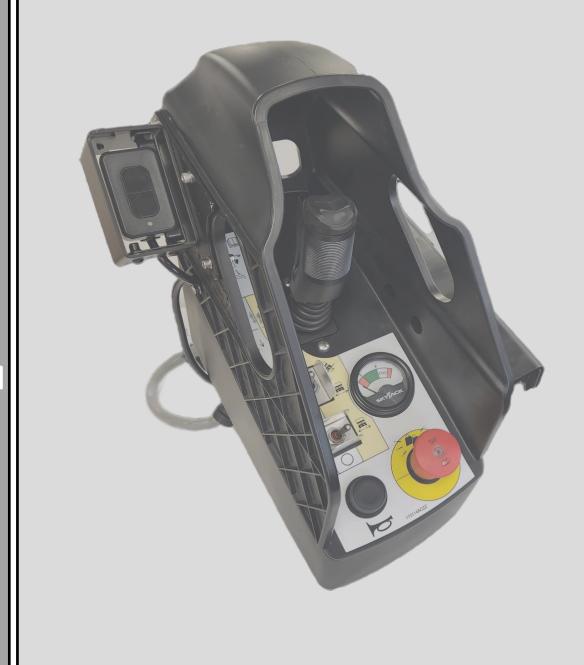
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18/01/2024

Model6253 OverWatch™ Installation Manual

Document # DO001386

EQSS Model6253 – OverWatch™ Skyjack Large RT Series



** Failure to follow this installation manual will void warranty **





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| | | |
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| DOCUMENT ABSTRACT: | | |
| This Installation Manual details the manufacture | cturer's installation instructions for installing | ng the Model6253 OverWatch on a |
| Skyjack Large RT Series Scissor Lift. | | |
| PRODUCT NAME: | | |
| Model6253 OverWatch Operator Detection | System | |
| Wilderozas aver water aperator beteetion | System | |
| | | |
| REFERENCE DOCUMENTS: | | |
| DO0001195 Model6253 OverWatch User M | anual | |
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Important Information

Information contained in this publication regarding this device's applications and the like, is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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Preparation

Required Tools

The OverWatch has been designed to be fitted using basic workshop tools. Shown below is a list of tools required to complete the installation.

| Item | Tool / Description |
|------|----------------------------|
| 1 | Electric Drill |
| 2 | Centre punch |
| 3 | Hammer |
| 4 | Side Cutters |
| 5 | Drill 5.2mm |
| 6 | Drill 6.5mm |
| 7 | Metric sockets or spanners |
| 8 | Needle nose pliers |
| 9 | Screw drivers |

Installation Time

The suggested time required to install the OverWatch is as detailed below.

| Task | Estimated Time (Minutes) |
|---|--------------------------|
| Open the operator control box | 1 |
| Drilling of all mounting holes for the various components | 13 |
| Mechanical assembly | 10 |
| Electrical assembly | 10 |
| Post installation system tests | 10 |
| Close the operator control box | 1 |
| Total | 45 |



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Installation Instructions

If any decals are damaged during the installation process or if any decals are obstructed following the installation, they should be replaced accordingly.

Operator Sensor

| Step | Description | Diagram |
|------|--|-------------------|
| 1. | Remove 6 bolts located at the bottom of the plastic enclosure to expose the internals of the operator control box. | |
| 2. | Drill five X 5.2mm holes in the locations shown in the diagram | 62.00mm ▼Thru x 5 |





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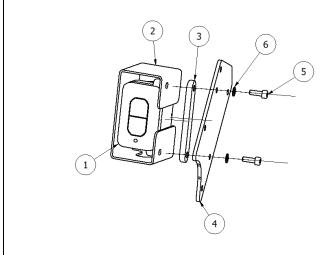
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3. Sensor Mounting Guard V1 (ME001794)

Install the Operator Sensor onto the mounting plate as shown in the diagram.

The wedge blocks must be orientated such that the sensor twists away from the joystick / control box. Such that when the operator is standing in position the sensor is pointing towards the centreline of the operator's body.

| | PARTS LIST | | |
|------|------------|-------------|---------------------------------|
| ITEM | QTY | PART NUMBER | DESCRIPTION |
| 1 | 1 | AS001910 | OverWatch Operator Sensor |
| 2 | 1 | ME001794 | OverWatch Operator Sensor Guard |
| 3 | 1 | ME001798 | Operator Sensor Alignment Wedge |
| 4 | 1 | ME001810 | Operator Sensor Mounting Plate |
| 5 | 2 | FA001417 | M4 x 12mm Security screw |
| 6 | 2 | FA001235 | M4 Plain Washer |

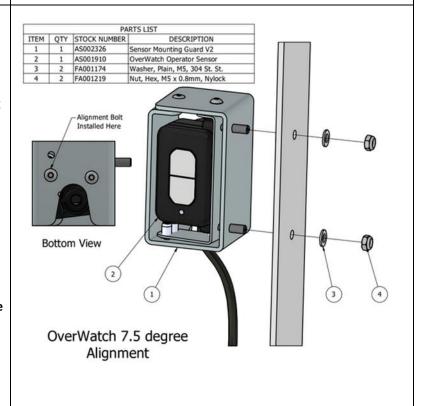


4. Sensor Mounting Guard V2 (AS002326)

This bracket (AS002326) supersedes the original V1 design. Attach the bracket in position using the M5 nuts and washers.

Make sure that the sensor is on the **7.5-degree angle**, such that it is twisted outwards from the joystick controller.

The 7.5-degree twist is achieved by rotating the sensor inside the assembly and using the bolt hole as shown in the image.





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5. Drill two **6.5mm** holes when using the Sensor Mounting Guard V2 (AS002326) to the control box as shown in the image.

These holes allow the mounting plate to sit flush by making room for the M5 nuts.







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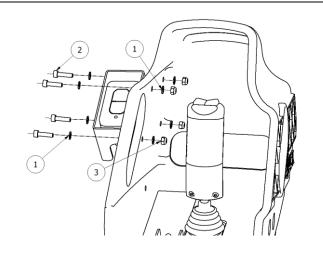
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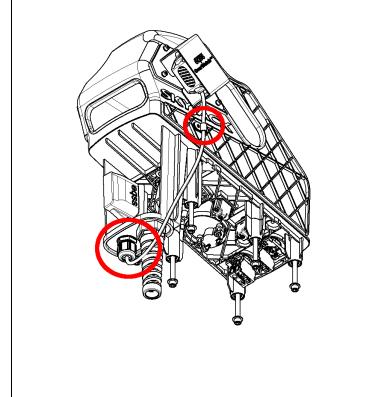
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6. Mount the operator sensor plate to the side of the control box using the nuts, bolts, and washes, as shown in the image.



| | PARTS LIST | | |
|------|------------|-------------|---------------------------------|
| ITEM | QTY | PART NUMBER | DESCRIPTION |
| 1 | 8 | FA001235 | M4 Plain Washer |
| 2 | 4 | FA001188 | M4 x 16mm Socket Head Cap Screw |
| 3 | 4 | FA001223 | M4 Nylock Nut |

7. Install the cable gland in the location shown in the diagram. Clamp the wire to the side of the enclosure using the supplied P-Clip.





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Control Module

| Step | Description | Diagram | | | |
|------|--|---------|-------------|----------------------|--|
| 1. | Drill two 4.2mm holes to mount the ECU as shown in the image. | | Ø4.2 X 2 | 0mm ₹Thru | 256.00mm = 65.00mm |
| 2. | Mount the ECU module using the bolts, nuts, and washers. | | 3 | 1 2 PA | RTS LIST |
| | | ITEM | QTY | PART NUMBER | DESCRIPTION |
| | | 1 | 2 | FA001235 | M4 Plain Washer |
| | | 3 | 2 | AS001916 FA001211 | OverWatch ECU Module M4 x 12mm Socket Head Screw |
| | | [3] | - | | A ZZIIIII SOURCE HEAU SCIEW |



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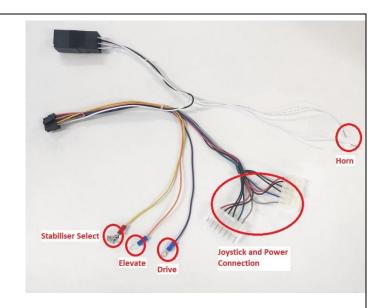
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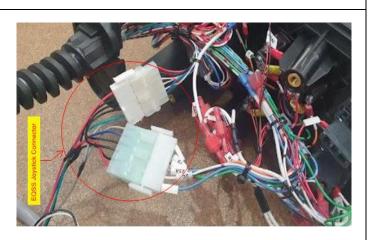
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3. Wiring connections are made with the AS002069 harness.



4. Joystick and Power:

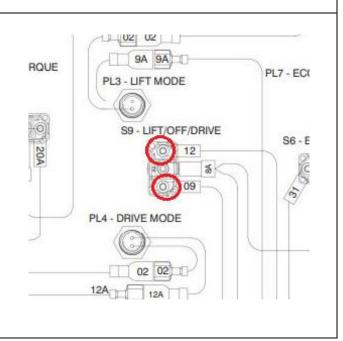
Disconnect the 6-Pin connector from the joystick and install the OverWatch harness in series with the connectors.



5. Elevate/ Drive Select Connection:

At the back of the Drive/Elevate switch,

Install the **orange** wire from the OverWatch harness to the wire id **09** and install the **purple** wire to the wire id **12**.





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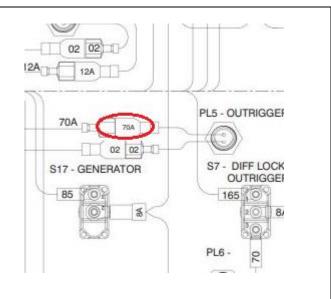
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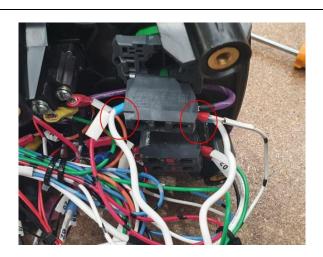
6. **Stabilizer Select Connection:**

Solder the **yellow** stabiliser select wire from the OverWatch harness to the back of the Stabiliser Light wire id 70A.



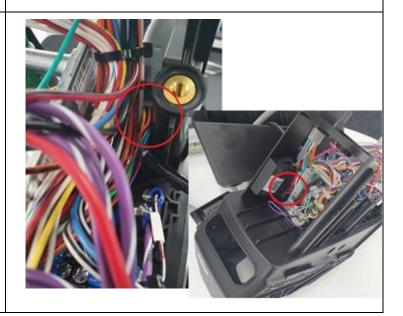
7. Horn Connection:

At the back of the horn push button, Install the **white** wires from the OverWatch harness to both sides of the switch block, as shown in the image.



8. Connect the 8-pin connector from the Operator Sensor and the 12-pin connector from the machine connection harness to the OverWatch ECU module

Use cable ties to combine the cables neatly together.





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9. Reassemble the control box and secure the operator sensor cable by using a cable tie.





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Post Installation Configuration

Overview

After the system has been installed it must be configured with the parameters to suit the machine. Follow the instructions below to configure the OverWatch.

Minimum system requirements

Any smartphone, tablet or laptop that meets the following requirements:

- The device can connect to a Wi-Fi access point
- The device has an up to date web browser installed. Firefox, Chrome or Safari are recommended.

Wi-Fi Connection & Web Page Access

To enable the Wi-Fi connection on the OverWatch to complete the configuration follow the steps below.

- 1. Power down the platform control box with the ESTOP
- 2. Wait 5 seconds
- 3. Power up the platform control box with the ESTOP
- 4. While standing in front of the operator sensor, switch on the OverWatch
- 5. As the welcome chime starts to play, cover the sensor. The LED will flash white then black to acknowledge.
- 6. Remove your hand from the sensor. The LED will flash white then black to acknowledge.
- 7. After covering then uncovering the sensor this way 2 more times, "Wi-Fi On" will be announced
- 8. On your Wi-Fi enabled device (laptop, tablet, smartphone, etc), show the available wireless networks
- 9. Select the wireless network (starts with "overwatch") to connect to the OverWatch
- 10. When prompted, enter the password 12345678
- 11. Open your preferred web browser (Chrome, Firefox, Safari)
- 12. Enter the following into the address bar http://192.168.4.1 to open the OverWatch main page



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Machine Model Selection

Follow the instructions below to configure the OverWatch.

- 1. Select the Setup option
- 2. If there is a password field at the bottom of the page, follow the instructions in Change Model Configuration to obtain the password and enter the password field
- 3. Select the EWP Model from the drop-down list and click Set
- 4. Click on Proceed to test to begin the installation test





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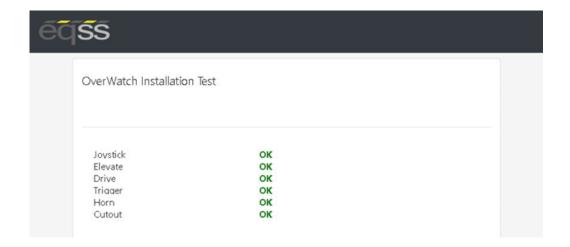
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Installation Test

After the model configuration has been set or updated an Installation Test must be performed. This will ensure the installation has been correctly performed and the OverWatch is functioning correctly. Follow the instructions on the web page to complete the Installation Test.







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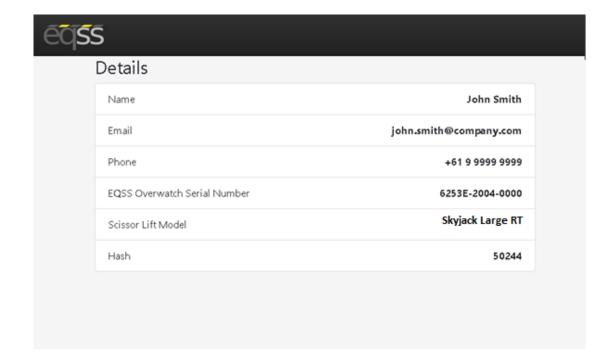
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Change Model Configuration

To reconfigure the OverWatch for a different model requires an authorisation password. The authorisation password is generated from the EQSS website. The EQSS website requires a login username and password, contact EQSS for these details.

Follow the instructions below to obtain an authorisation password. It is important to note that each ECU has a unique serial number and a unique password.

- 1. Open your web and enter the following into the address bar http://www.eqss.com.au/overwatch to open the Login page
- 2. Enter your username and password
- 3. Enter the EUC serial number which is shown on the setup page or on the ECU serial number sticker, also enter the owner and model details of the EWP and then click Generate Hash
- 4. The generated Hash code or password can be used to change the model configuration.





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System Settings

Default Parameters

The OverWatch is configured with the following default parameters.

| Setting Name | Description | Default |
|-------------------------------|---|---------|
| max_safe_velocity | This is the velocity threshold for the cutout in cm/s for drive mode. | 95 |
| max_safe_displacement | This is the maximum permitted distance in cm the operator may be away from the calibration position in drive mode. | 50 |
| max_safe_velocity_elevate | This is the velocity threshold for the cutout in cm/s for elevate mode. | 75 |
| max_safe_displacement_elevate | This is the maximum permitted distance in cm the operator may be away from the calibration position in elevate mode. | 50 |
| fwddispadj | The proportion of the calibration distance toward the sensor permitted to the operator. | 0.7 |
| fwdveloadj | The coefficient to apply to the maximum allowable velocity when the movement of the operator is toward the sensor. | 1.0 |
| zone_obstruction | If the lidar sensor reading is below this, the lidar is considered to be obstructed (with paint or thick coat of dust) and the system is cutout until the obstruction is cleared. | 5 |
| zone_minimum | The minimum calibration distance. If the operator is closer to the sensor than this "operator zone" will be announced. | 17 |
| zone_maximum | The maximum calibration distance. If the operator is further from the sensor than this "operator zone" will be announced. | 120 |
| adc_elevate_threshold | Threshold value for the elevate ADC input. | 500 |
| adc_drive_threshold | Threshold value for the drive ADC input. | 500 |
| adc_trigger_threshold | Threshold value for the trigger ADC input. | 500 |
| adc_joystick_fwd_threshold | Forward threshold value for the joystick ADC input. | 1450 |
| adc_joystick_bwd_threshold | Backward threshold value for the joystick ADC input. | 1350 |
| throttle_time | Period after the trigger is pressed (ms) during which initial velocity reading is computed. | 500 |
| driving_state_timeout | Mode selection switch timeout (ms) | 7000 |





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Polarity and Input Style

The table below describes each setting

| Setting Name | Description | Default |
|-------------------------|---|---------|
| joystick_drive_forward | Direction of joystick to move EWP forward | forward |
| joystick_elevate_upward | Direction of joystick to move EWP upward | forward |
| elevate_polarity | Direction of signal logic | high |
| drive_polarity | Direction of signal logic | high |
| trigger_polarity | Direction of signal logic | high |
| joystick_polarity | Direction of signal logic | high |
| driving_state_input | Direct, timer based or separate joysticks | direct |

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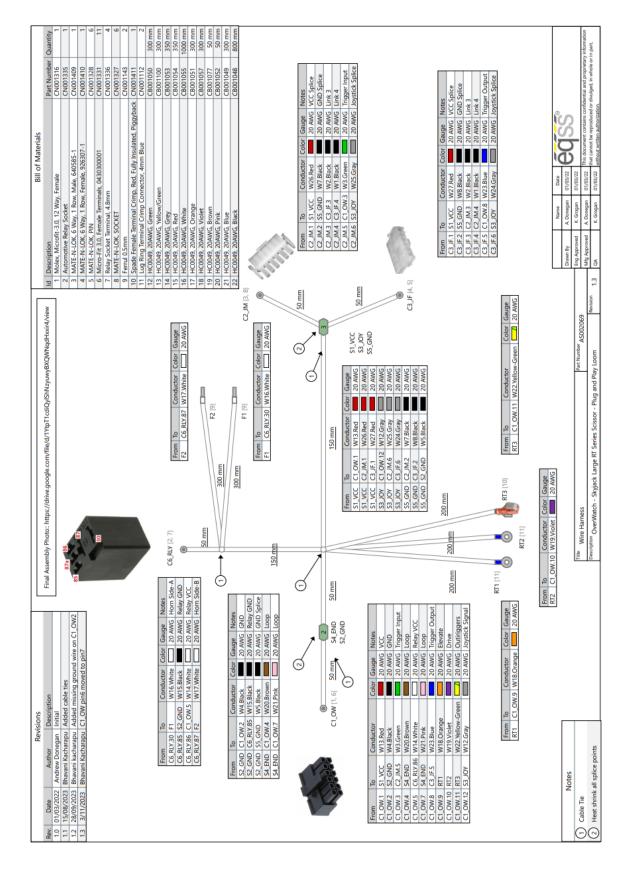
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Harness Drawing AS002069





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Replacement Parts

Replacement parts for this OverWatch kit are available from EQSS, please email sales@eqss.com.au Shown below are the part numbers for the major components included in this model specific kit.

| Part Number | Description |
|-------------|--|
| AS002068 | OverWatch - Complete kit for Skyjack Large RT series |
| AS001910 | OverWatch - Operator sensor with M20 gland |
| AS001916 | OverWatch - Electronic Control Unit (ECU) |
| AS002069 | OverWatch – Skyjack Large RT series harness |
| AS002326 | OverWatch - Sensor guard V2 |
| ME001810 | OverWatch - Sensor mounting plate |