

eqss™ Gen-3 LMS Telehandler Load Management System

Installation Manual for TL30.60



Do Not Swap Components between Gen3-LMS kits When installing multiple Gen3-LMS kits, make sure the serial number on the sticker matches the serial number on the machine.

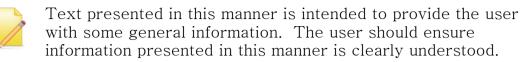
Failure To Follow Installation Manual Will Void Warranty

VER: 1905201039

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Documentation Conventions

The list below highlights important documentation conventions.



with some general information. The user should ensure information presented in this manner is clearly understood.



Text presented in this manner provides the user with information to assist in completion of the current procedure being explained.



Text presented in this manner indicates that a failure to follow directions could result in damage to equipment, loss of information, bodily harm, or loss of life.

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Tools Required for Installation

The tools required to perform the installation of the TSS are listed below

- Pencil or Texta
- Drill
- Drill bits
 - 3.3 mm
 - 4.5 mm
 - 5 mm
 - 6.8 mm
 - 8.5 mm
- Centre punch
- Tap T-Handle
- Taps
 - M6
 - M8
- Drill and tap oil
- Metric Allen keys
- Phillips Head screw driver
- Spanners and sockets
 - **7 mm**
 - 10 mm
 - 13 mm
- Locktite thread locker
- Side cutters
- Stanely knife
- Crimpers
- Wire strippers
- Torque Wrench

Installation Index

The components and cables of the Gen-3 Telehandler Load Management System are outline in the tables below. The following pages show where the components are installed and the cable routing.

See the appropriate manual section for a detailed installation description for each component.



Refer to this section for any component placement or cable routing issues

Item	Component Description
1	Cable Reeler
2	Main Lift Cylinder Pressure Sensors
3	Compensation Cylinder Pressure Sensors
4	Can Pressure Input Module (CPIM)
5	Cutout Connections
6	Lock Pin Release Connection
7	Forward Camera
8	Signal Light
9	Rear Camera

Table 1: Component Installation Index

Colour	Cable Description
Light Purple	Boom Cable
Dark Green	Main Cylinder Pressure Sensor Cables
Dark Blue	Compensation Cylinder Pressure Sensors Cables
Red	Cutout Harness
Orange	Lock Pin Release Harness
Light Green	Forward Camera Cable
Brown	Signal Light Cable
Light Blue	Rear Camera Cable
Dark Purple	CCIM Cable

Table 2: Cable Installation Index



Illustration 1: Machine Boom



Illustration 2: Machine Chassis

Covers

Remove the following covers before starting the installation

Step	Description	Diagram
1.	Remove the cover behind the cabin in front of the rear left wheel.	
2.	Remove the covers underneath the boom	
3.	Remove the cover in front of the cabin behind the front left wheel.	

Step	Description	Diagram
4.	Remove the cover under the steering wheel.	
5.	Undo the bolts attaching the dashboard.	

Table 3: Cover removal

Cable Reeler Installation

The cable reeler is used to measure the boom extension to determine the maximum lifting capacity.



A false N07 fault can occur if the boom jumps off the stow switch due to pressurising the hydraulic system and without operating the boom extension control. Ensure the stow switch arm is correctly adjusted to prevent this error.

Step	Description	Diagram
1.	Drill the holes for the cable reeler mounting plate according to the mounting diagram on page 13. Mount using the supplied M8 x 30 mm bolts, nuts and washers.	
2.	Drill and tap an M8 hole for the cable anchor. Ensure the cable anchor is positioned so the cable runs in line with the boom. Mount the cable anchor and attach the cable.	
3.	Drill and tap the M6 holes for the stow switch trigger bracket.Mount the stow switch trigger bracket using the supplied M6 x 12 mm bolts and washers.Adjust the length of the trigger plate to ensure the stow switch is pressed when the boom is retracted.	

Step	Description	Diagram
4.	Connect the supplied M12 10 metre cable (CB001027) into the cable reeler connection.	
5.	Run the cable under the boom and cable tie to the existing cable for the boom lights every 500 mm down the boom.	
	Cable tie to the flexible hydraulic hoses down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	
	Cable tie with the other cables during External Cable Completion on page 27.	

Table 4: Cable Reeler Installation



For further details on running the boom cable refer to the Installation Index on page 6

Cable Reeler Mounting Position



Illustration 3: Cable Reeler Mounting Position

Pressure Sensor Installation

The hydraulic pressure sensors are used to measure the lifting load of the telehandler.

Main Cylinder Pressure Sensors

Step	Description	Diagram
1.	 Raise the boom to approximately 40 degrees. Support and secure the boom using an A Frame or similar apparatus. It must support at least 2 tons. Apply the handbrake and insert chock under wheels. Remove the hose connections into the hydraulic manifold block. 	
2.	Release the bolts attaching the manifold block to the cylinder. Removing the bolts in the manifold block will release the hydraulic pressure which may result in a spray of oil. Secure the supplied pressure manifold plate to the existing manifold and through to the cylinder using the supplied bolts and seals. Tighten the 12.9 grade bolts for the manifold to 41 NM using a torque wrench. Reinstall the manifold block to the cylinder and reattach the hoses.	<image/> <caption></caption>

Step	Description	Diagram
3.	Ensure the hydraulic hoses are not resting on the pressure sensors. Start the machine, pressurise the boom and check for leaks and check for clearance.	Ensure hoses do not rest on pressure sensors.
4.	Shift the rear bracket, that holds the relays and fuses located behind the cabin, upward 20mm following the same centre-line as the current holes. This step is done to ensure the Manifold does not hit the bracket. ************************************	

Step	Description	Diagram
5.	Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.	
	Cable tie the pressure sensor cable to the flexible hydraulic hoses connected to the main lift cylinder. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	
	Run the cables towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 27.	View from under the boom
	Ensure the pressure sensors and cables do not collide with the boom and chassis structures and the cables do not stretch or pinch when the boom is raised and lowered.	

Table 5: Pressure Sensor Installation

Compensation Pressure Sensors

Step	Description	Diagram
1.	Undo the flexible hydraulic hose connections into the compensation cylinder. Install the supplied head and rod pressure sensors and tee	Rod
	connections as shown and reconnect the flexible hydraulic hose.	Head
	Ensure the pressure sensors don't hit when the boom is raised and lowered.	View from under the boom behind
	Start the machine, pressurise the boom and check for leaks and check for clearance.	the rear left wheel.
2.	Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.	
	Cable tie the pressure sensor cables to the flexible hydraulic hoses connected to the compensation cylinder down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	Red
	Run the cables towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 27.	View from under the boom behind the rear left wheel.

Table 6: Compensation Pressure Sensor Installation

Reverse Camera

The rear camera video is displayed on the screen when the machine is in reverse gear to allow the operator to see behind the telehandler while reversing.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Drill two M6 holes to mount the camera in the location shown.	
2.	Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032). Note; The white connector is not used. Secure the camera cable to the license plate light harness using cable ties. Run the remainder of the cable towards the cabin and insert into snake tube with the cabin cable during External Cable Completion on page 27.	

Table 7: Reverse Camera Installation



The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.

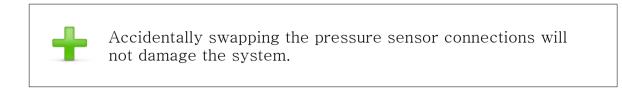
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For further details on running the camera cable refer to the Installation Index on page 6

Can Pressure Input Module (CPIM)

The CPIM is responsible for processing the information send from the pressure sensors.





Do not plug the pressure sensor cable into the far right side boom cable. This will damage the system.

Step	Description	Diagram
1.	The CPIM module is mounted on the inside of the chassis just behind the cabin. Place the CPIM module on the outside of the chassis and mark the drill hole location. Ensure the location will allow enough clearance to mount the CPIM and attach the M12 cables at the bottom and sides. Drill two M8 holes through the side of the chassis and mount the CPIM using the supplied bolts.	<image/>

Step	Description	Diagram
2.	Connect the cables for the pressure sensors and boom cable to the CPIM according to the labels on the CPIM sticker Note: The CCIM cable will be	
	installed during External Cable Completion on page 27.	

Table 8: Can Pressure Input Module (CPIM) Installation

Signal Light Installation

The signal light warns other workers when the telehandler is lifting loads close to it's maximum capacity.



Ensure the power supply voltage is greater than 13.5V otherwise the signal light may not illuminate correctly.

Step	Description	Diagram
1.	Windshield Guard Mount the signal light to the top windscreen guard using the supplied p-clips.	View from on top of the cabin
2.	Without Windshield Guard Magnetically mount the signal light of the top of the roof as shown.	view nom on top of the cubit

Step	Description	Diagram
3.	Run the signal light cable down towards the cabin grommet and secure in place using the cable tie adhesive strips.	
4.	Inside the cabin remove the cover on the roof to access the cabin grommet. Cut 200mm from the connector end of the light tower cable in order to feed the cable through the rear roof grommet. It will be re-attached to the connector at a later stage.	
5.	Run the end of the cable through the grommet leading into the cabin and feed it through the grommet out to the top of the roof inside the cabin.	
6.	Reconnect the 4 wire cable using the supplied crimp joiners. The snake tube will need to be removed to run the cable through the grommet. Once all the cable has been feed into the cabin, reattach the snake tube starting where the cable runs out the grommet from the roof.	

Step	Description	Diagram
7.	Run the signal light cable along the roof to the other side of the cabin.	
8.	Run the cable from the roof and secure in place using the cable tie adhesive strips. Run the cable under the plastics covers to the dashboard, to connect into the CCIM.	

Table 9: Signal Light Installation

Forward Camera

The forward camera video is displayed on the screen when the machine is in forward gear to allow the operator to see past the boom to obstructions that would damage the right front tyre.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Mount the camera to the side mirror post using the p-clips as shown. Secure using two M6 nuts.	
2.	Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032). Note; The white connector is not used. Run the cable along the same path as the headlight cable through the headlight post. Run the remainder of the cable towards the cabin following the headlight cable and insert into cabin during External Cable Completion on page 27.	

Table 10: Forward Camera Installation



The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



For further details on running the camera cable refer to the Installation Index on page 6

External Cable Completion

All external cabling is completed in this step.

Step	Description	Diagram
1.	Locate the cable entrance hole from the inside of the cabin to the outside of the chassis, located inside the dashboard to outside the front of the cabin.	View from behind the front left wheel towards the cabin
2.	Run the two pin connector pairs from the cutout and lock pin release harnesses through the connector hole from inside the cabin to the outside of the chassis.	
3.	Connect the supplied M12 4 metre cable (CB001026) into the right side of the CPIM for the CCIM cable.	M Head C C C M Head B Boom d d d d d d d d d d d d d d d d d d

Step	Description	Diagram
4.	Run the cutout and lock pin release harnesses along the same path under the chassis covers as the existing electrical harnesses and hydraulic lines towards the spool assembly at the rear of the machine.	
	Run the CCIM and rear camera cables along the same path as the existing electrical harnesses and hydraulic lines towards and through the hole into the cabin.	
5.	Run the two pin connectors on the lock pin release harness up to the lock pin release solenoid valve and secure in place using cable ties. This will be connected into the solenoid valve during Finalisation on page 40.	
6.	Run the pair of two pin connectors on the height limit cable from out the side of the CPIM module and the two pin connectors from the cutout harness through the hole in the chassis to the spool assembly.	

Step	Description	Diagram
7.	Connect into the spool assembly as shown and secure in place using cable ties. Once secure remove the connections so that the boom will function. These will be reconnected into the solenoid valves during Finalisation on page 40.	Raise Extend
8.	Coil up the additional cabling for the pressure sensor, CCIM and boom cables and store underneath the CPIM.	View from behind the cabin

Step	Description	Diagram
9.	Run the CCIM, signal light and camera cables up through the hole into the cabin.	
	Note: Pull a short length of cable through into the cabin. Store excess cable under the covers below the boom, ensure they will not wrap around the drive shaft.	

Table 11: External Cable Completion

Display Installation

The display shows the current safety status of the telehandler.

Step	Description	Diagram
1.	Remove the rear mirror from the right colomn.	
2.	Using the supplied M3 screws, Plastic Sleeve, and bolts, mount the Display Bracket to the same mounting location of the removed rear-view mirror. Mount the display to the installed display-bracket and connect the 2 X M12 screw-lock connectors to the back of the display.	

Table 12: Display Installation



Adjust the display bracket for optimal viewing angle once the display is powered



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 49 for the correct method of attaching to the display connectors.

User Input Control

The user input control consists of a single dial switch mounted in the dashboard.

Step	Description	Diagram
1.	Drill a 34 mm hole into the location shown shown below the park brake switch. Install the user input control dial in the dashboard, aligned so the Enter cap is facing up.	

Table 13: User Input Control Installation

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If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 49 for the correct method of attaching to the display connectors.

Can Cabin Interface Module (CCIM)

The CCIM connects the system into the machine electronics.

Step	Description	Diagram
1.	Position the backup battery (shown behind the CCIM) to the side panel underneath the dashboard using double sided velcro tape. Position the CCIM in front of the backup battery using double sided velcro tape. Remove the battery and CCIM from the velcro to allow the connections to be completed. Reattach to the velcro in the section Finalisation on page 40.	Wiew from inside dashboard

Table 14: CCIM Installation

Machine Connections

The following procedures connect the safety systems to the existing electronics in the machine.



Isolate the main battery before starting the machine connections



After completing the machine connections the boom can not be moved until the installation is complete

Step	Description	Diagram
1.	Remove a blanking switch plate from the removable dashboard panel and install the camera switch. Connect the male spade connections from the machine input harness to the camera switch according to the table below. <u>Wire Colour</u> Terminal	
	Blue 1	
	Black 2	
	Green 3	

Step	Description	Diagram
2.	Locate the override switch terminal C218 in the removable dashboard panel.	
	Remove the fork terminal connected to blue wire #3310 from the override switch terminal and replace with the violet wire from the machine input harness.	
	Cut off the fork terminal on the blue wire #3310 and join to the yellow wire from the machine input harness.	
3.	Locate the ground lug near the bulkhead connectors attached to the side of the chassis.	A Martin Providence
	Attach the ring lug from the machine input harness to the ground lug.	
	Secure using the supplied M6 bolt.	
		View from the from the floor of the cabin towards the middle of the machine
4.	Locate the ignition key switch terminal C210 in the removable dashboard panel.	
	Connect the 6 pin tee connection on the power harness into the C210 connector.	
		View behind the dashboard

Step	Description	Diagram
5.	Attach the ring lug from the power harness to the ground lug, located earlier.	View from the from the floor of the cabin towards the middle of the machine

Table 15: Machine Connections

Cabin Loom

The cabin loom connects the CCIM to the machine connections and the other modules of the system.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Connect the CCIM and signal light cables to the M12 connectors on the CCIM. Note: It doesn't which of the M12 connectors the CCIM and signal light cables are plugged into.	Cartera / Power I/O CAN
2.	Connect the power/camera and IO harnesses to the CCIM bulk head connectors	
3.	Connect the forward and reverse cables to the power/camera harness. Note; The white connector is not used.	

Step	Description	Diagram
4.	Connect the 4 pin connector from the machine input harness into the IO harness.	
	Connect the 6 pin connector from the machine cutout harness to the IO harness.	
	Connect the 12 pin connector from the lock pin release harness to the IO harness.	
	Note: The 2 pin connection on the IO harness is not used.	
5.	Run the 8 pin CCIM cable and the 5 pin user control cable through the gap between the window and the dashboard. Note: The clip-on ferrites will need to be removed to run the cables through the gap between the window and the dashboard. Reattach the ferrites according to Appendix A: Attaching Display Connectors on page 49.	
6.	Run the cables through snake tube. Place cable tie points on the side of the window. Cable tie the snake tube to the cable tie points. Connect into the 8 pin and 5 pin connectors into the display	

Step	Description	Diagram
7.	Connect the spade lug on the black wire to the negative (black) battery terminal on the backup battery. Connect the spade lug on the blue wire to the positive (red) battery terminal on the backup battery.	

Table 16: Cabin Loom Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 49 for the correct method of attaching to the display connectors.



If the clip-on ferrites were removed from the CCIM and user control cables. See Appendix B: Reattach Ferrites and page 53 for the correct reattachment position.

Finalisation

This section will complete the final power connections to power the system and finish any additional items.

Step	Description	Diagram
1.	Connect the 3 pin connector from the radio power harness into the power/camera harness. Coil up and store the wire harnesses under the dashboard.	
2.	Attach the backup battery to the velcro on the CCIM and attach the CCIM to the velcro installed earlier to the cabin chassis	View from the from the floor of the cabin towards the steering column
3.	Reconnect the tee connectors back into the spool assembly and the lock pin release solenoids.	

Step	Description	Diagram
4.	Turn the machine onto first stage/accessories and ensure the system is activated.	
	Adjust the display bracket for optimal viewing	
	Press the top of the Camera switch to active the forward camera. Adjust the forward camera so the front right wheel is visible.	
	Press the bottom of the Camera switch to active the reverse camera. Adjust the reverse camera so the video is level.	
5.	Operate the boom movement controls to test if a false N07 fault occurs.	
	If a N07 fault does occur, adjust the arm on the stow switch forwards towards the stow switch trigger.	
	Note: The actual switch arm orientation may differ from the picture.	
6.	Perform a final check on all the cabling and sensors.	
	Replace all the covers	

Table 17: Finalisation

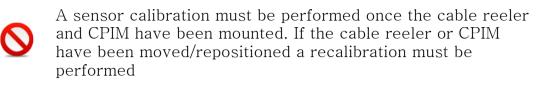


Complete the system checklist once installation has been completed.

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Set Time & Sensor Calibration

Once the installation is complete, the time will need to be set and the sensors will require calibration.



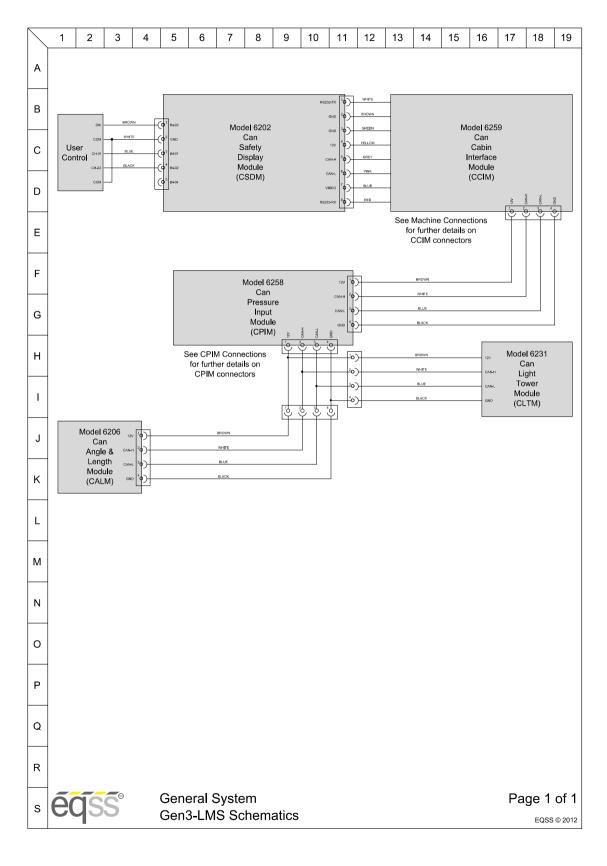
Step	Description	Diagram
1.	Press Enter on the user control dial	Main Menu
	to enter the menu system.	Attachment Selection Menu
	Press the arrow buttons to select System Menu.	
	Press Enter to select the menu.	System Menu
		Exit Menu
2.	Select Advanced Menu	System Menu
		Volume / Brightness
		Status Menu
		Diagnostics Menu
		System Tests
		Advanced Menu
		Return to Main Menu

Step	Description	Diagram
3.	Enter the password	Enter Password
	(Default Password: 2-8-4)	Number 1 2
		Number 2 8
		Number 3 4
		Submit Password
		Return to System Menu
4.	Select Set Time / Date	Advanced Settings
1.	Scheet Set Time / Date	Set Time / Date
		Sensor Calibrations
	-	Change Language
		Change Password
		Return to System Menu
5.	Enter the correct time and date for	Set Time / Date
0.	your area.	Hour 15
	Press the arrow keys to select a	Minute 54
	time/date parameter	Day 10
	Press Enter and the parameter will change to red, press the arrow keys to change the value and then press the Enter key to store the value.	Month 2
		Year 2016
		Region Melbourne
	Note: The hour parameter is in 24 hour clock	
	Repeat for the rest of the time values	

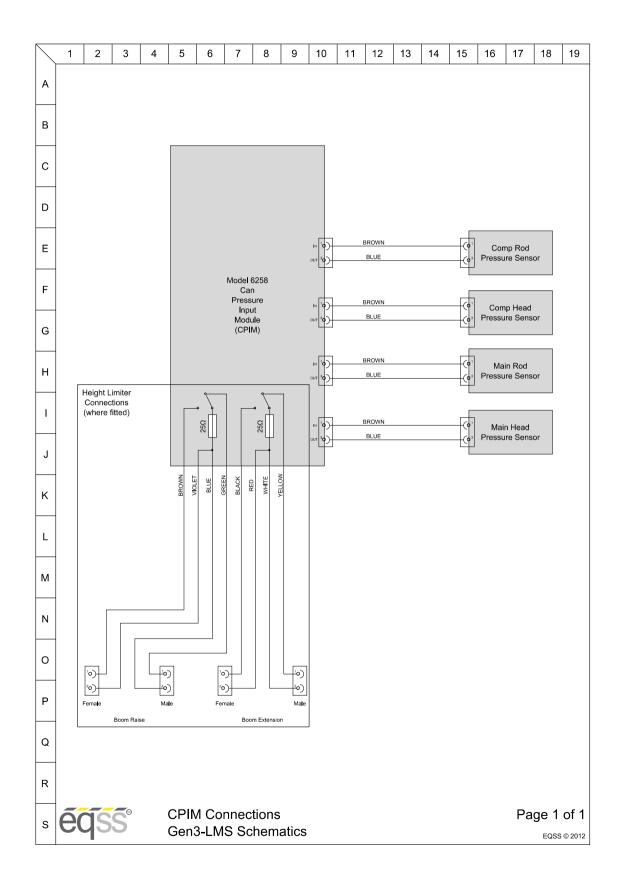
Step	Description	Diagram
6.	Scroll to the next page and select Save to store the new time/date and	Save
	return to the Advanced Menu.	Return to Advanced Menu
7.	Select Sensor Calibrations	Advanced Settings
		Set Time / Date
		Sensor Calibrations
		Change Language
		Change Password
		Return to System Menu
8.	Select Calibrate Carrier Angle and	Sensor Calibration Menu
	then follow the instructions on the	Calibrate Carrier Angle
	screen to complete the calibration.	Calibrate Boom Angle
	Repeat for Calibrate Boom Angle and Calibrate Boom Length.	Calibrate Boom Length
		Return to Advanced Menu

Table 18: Sensor Calibration

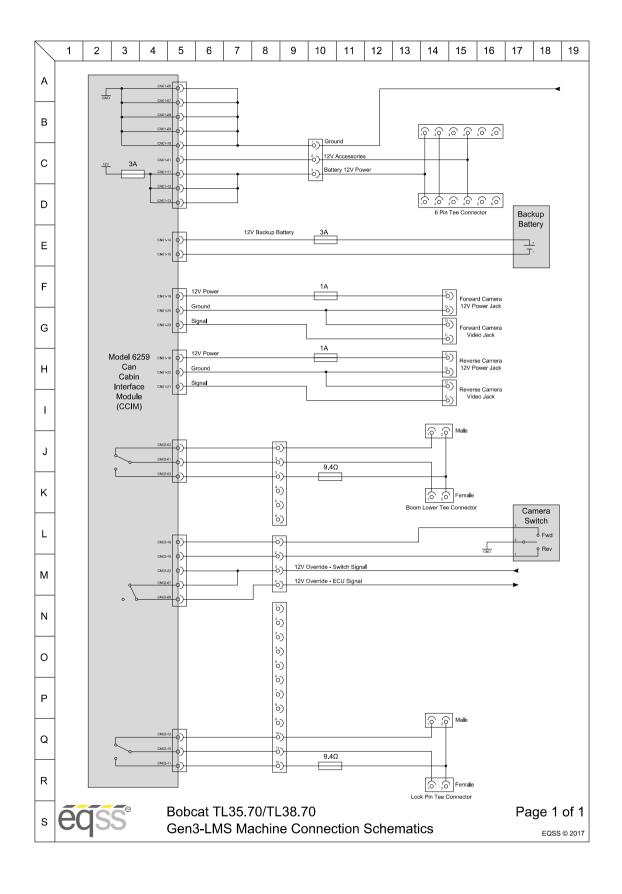
Schematics



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Appendix A: Attaching Display Connectors

The procedure below describes the correct method of attaching the cables to the screw lock connectors on the display.

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If the M12 screw lock connectors on the display are over tightened, it will twist the connector pins attaching the connector to the PCB.

Step	Description	Diagram
1.	Connect the cable from the user control to the top 5 pin connector on the display. Connect the cable from the CCIM to the bottom 8 pin connector on the display.	Image: Second state of the second s
2.	Line up the alignment hole on the cable connector with the alignment notch on the display connector.	

Step	Description	Diagram
3.	Push the female connector from the cable into the male connector on the display.	
4.	Rotate the nut on the female connector by hand in a clockwise direction, until the tension on the nut starts to increase.	
5.	Push the cable in again and repeat steps 3 and 4 until the connector is secure.	

Table 19: Install Display Connector Procedure



The method to correctly secure the cable is to push-twistpush-twist until the connector is fully inserted and secure. This will minimise the twisting force applied to the connector.

Below is a picture of a damaged connector on the PCB inside the display. This damaged occurred because the connector was over tightened.

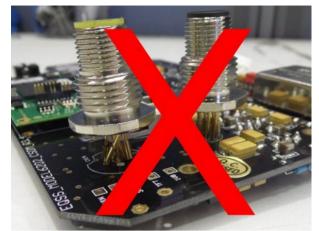


Illustration 4: Damaged Display Connector



Do not use any tools to tighten the connector.



Illustration 5: Do Not Use Tools To Tighten Connector



Do not over-tighten the nuts on the back of the display connectors. These nuts should only be hand tightened. If the nuts are overtightened it will damage the PCB inside the display.



Illustration 6: Do Not Over Tighten Nuts



Damage to the display connectors is not covered under warranty.

Appendix B: Reattach Ferrites

If the clip-on ferrites on the displays are removed during installation, they will need to be reattached as shown in the procedure below.



If the ferrites are not reinstalled or attached in the specified location the Gen3-LMS kit will not meet the AS/NZS CISPR 22:2006 certification.

Step	Description	Diagram
1.	Attach the two clip-on ferrites at a location of 60 mm and 260 mm from the start of the connector to the start of the ferrite. Do this for both the CCIM and user control cables that plug into the display.	

Table 20: Reattach Ferrites Procedure

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