

# eqss™ Gen-3 LMS Telehandler Load Management System

Installation Manual for TL35.70 2022 Model





\*\*\*Do Not Swap Components between Gen3-LMS kits\*\*\*

When installing multiple Gen3-LMS kits, make sure the serial number on the sticker matches the serial number on the machine.

\*\*\*Failure To Follow Installation Manual Will Void Warranty\*\*\*

#### **Documentation Conventions**

The list below highlights important documentation conventions.



Text presented in this manner is intended to provide the user with some general information. The user should ensure information presented in this manner is clearly understood.



Text presented in this manner provides the user with information to assist in completion of the current procedure being explained.



Text presented in this manner indicates that a failure to follow directions could result in damage to equipment, loss of information, bodily harm, or loss of life.

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#### **Important Information**

Information contained in this publication regarding this device's applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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# **Tools Required for Installation**

The tools required to perform the installation of the TSS are listed below

- Pencil or Texta
- Drill
- Drill bits
  - 。 3.3 mm
  - 4.5 mm
  - 。 5 mm
  - 。 6.8 mm
  - 。 8.5 mm
- Centre punch
- Tap T-Handle
- Taps
  - 。 M6
  - 。 M8
- Drill and tap oil
- · Metric Allen keys
- · Phillips Head screw driver
- Spanners and sockets
  - 。 7 mm
  - 。 10 mm
  - 13 mm
- Locktite thread locker
- Side cutters
- Stanely knife
- Crimpers
- · Wire strippers
- Torque Wrench

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## **Installation Index**

The components and cables of the Gen-3 Telehandler Load Management System are outline in the tables below. The following pages show where the components are installed and the cable routing.

See the appropriate manual section for a detailed installation description for each component.



Refer to this section for any component placement or cable routing issues

Item	Component Description
1	Cable Reeler
2	Main Lift Cylinder Pressure Sensors
3	Compensation Cylinder Pressure Sensors
4	Can Pressure Input Module (CPIM)
5	Cutout Connections
6	Lock Pin Release Connection
7	Forward Camera
8	Signal Light

Table 1: Component Installation Index

Colour	Cable Description	
Light Purple	Boom Cable	
Dark Green	Main Cylinder Pressure Sensor Cables	
Dark Blue	Compensation Cylinder Pressure Sensors Cables	
Red	Cutout Harness	
Orange	Lock Pin Release Harness	
Light Green	Forward Camera Cable	
Brown	Signal Light Cable	
Dark Purple	CCIM Cable	

Table 2: Cable Installation Index

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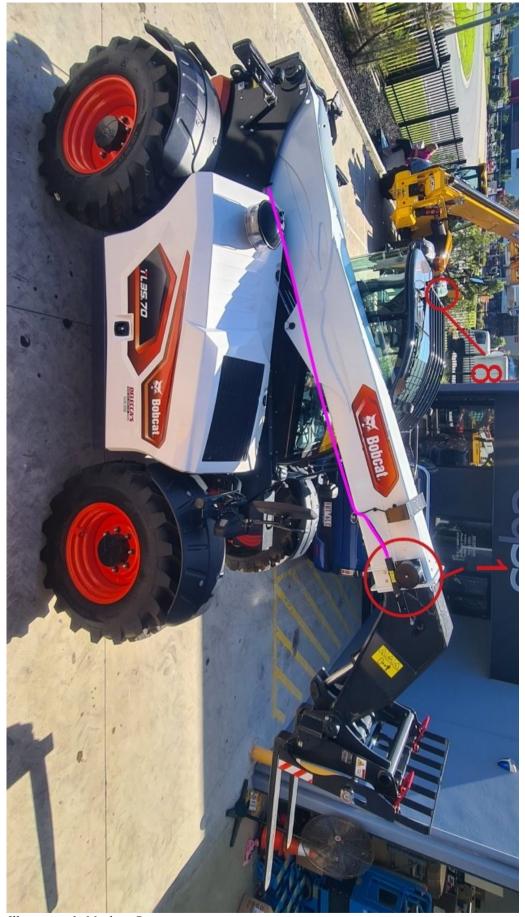


Illustration 1: Machine Boom



Illustration 2: Machine Chassis

### Covers

#### Remove the following covers before starting the installation

Step	Description	Diagram
1.	Remove the rear covers and disconnect the license plate light and reverse camera.	
2.	Remove the side panel next to the cabin and panels under the boom.	
3.	Remove the dashboard panel and cover under the steering wheel.	

Table 3: Cover removal

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#### **Cable Reeler Installation**

The cable reeler is used to measure the boom extension to determine the maximum lifting capacity.



A false N07 fault can occur if the boom jumps off the stow switch due to pressurising the hydraulic system and without operating the boom extension control. Ensure the stow switch arm is correctly adjusted to prevent this error.

Step	Description	Diagram
1.	Drill the holes for the cable reeler mounting plate according to the mounting diagram on page 13.  Mount using the supplied M8 x 30 mm bolts, nuts and washers.	
2.	Drill and tap an M8 hole for the cable anchor. Ensure the cable anchor is positioned so the cable runs in line with the boom.  Mount the cable anchor and attach the cable.	
3.	Drill and tap the M6 holes for the stow switch trigger bracket.  Mount the stow switch trigger bracket using the supplied M6 x 12 mm bolts and washers.  Adjust the length of the trigger plate to ensure the stow switch is pressed when the boom is retracted.	

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Step	Description	Diagram
4.	Connect the supplied M12 10 metre cable (CB001027) into the cable reeler connection.	

Description Step Diagram 5. Run the cable down the boom, cable tie to the existing light harnesses down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered. Cable tie with the other cables during External Cable Completion on page 22.

Table 4: Cable Reeler Installation



For further details on running the boom cable refer to the Installation Index on page 6

## **Cable Reeler Mounting Position**

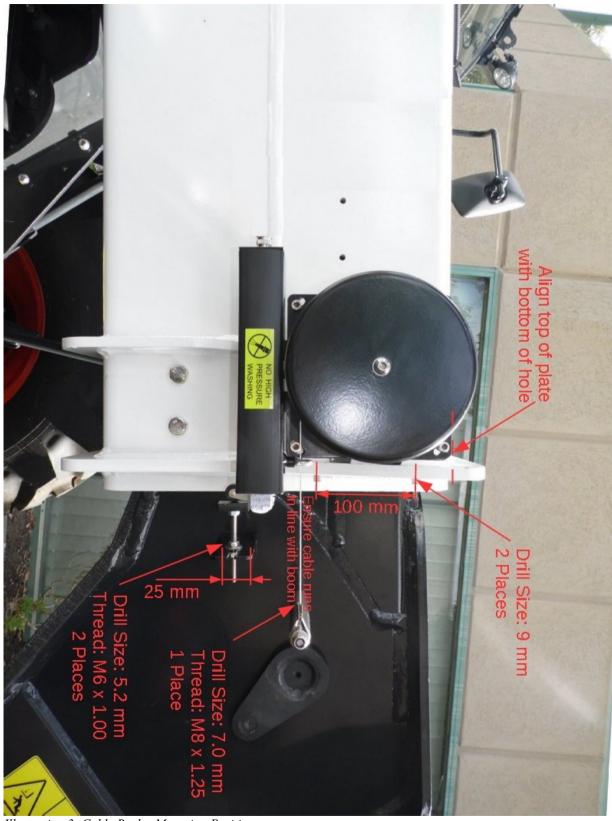


Illustration 3: Cable Reeler Mounting Position

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#### **Pressure Sensor Installation**

The hydraulic pressure sensors are used to measure the lifting load of the telehandler.

#### **Main Cylinder Pressure Sensors**



Failure to tighten the bolts to the correct torque on the pressure manifold may result in a pressure failure on the counterbalance valve causing an uncontrolled fall of the boom.

#### Step Description Diagram 1. Raise the boom to approximately 40 degrees. Support and secure the boom using an A Frame or similar apparatus. It must support at least 2 tons. Apply the handbrake and insert chock under wheels. Remove the counterbalance valve on the side of the hydraulic lifting ram. View from under the boom behind It's not necessary to disconnect the the rear right wheel attached hoses. Removing the counterbalance valve will release the hydraulic pressure which may result in a spray of oil. Slide the pressure manifold between the cylinder and existing counterbalance valve manifold, this may required slightly bending the fixed hydraulic pipe connected to the accumulator. Secure the pressure manifold using Use lube on seals to hold in place the bolts and seals supplied. Tighten during mounting the 12.9 grade bolts for the manifold to 41 NM using a torque wrench. Start the machine, pressurise the boom and check for leaks and check for clearance between bottom of the boom and the manifold.

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Step	Description	Diagram
2.	Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.	
	Cable tie the pressure sensor cable to the flexible hydraulic hoses connected to the main lift cylinder. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	HEAD
	Run the cables towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 22.	View from rear right wheel
	Ensure the pressure sensors and cables do not collide with the boom and chassis structures and the cables do not stretch or pinch when the boom is raised and lowered.	View from under the boom behind the rear left wheel

Table 5: Pressure Sensor Installation

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### **Compensation Pressure Sensors**

Step	Description	Diagram
1.	Undo the flexible hydraulic hose connections into the compensation cylinder.  Install the supplied head and rod	TO T
	pressure sensors and tee connections as shown and reconnect the flexible hydraulic hose.	HIM
	Ensure the pressure sensors don't hit when the boom is raised and lowered.	View from under the boom behind
	Start the machine, pressurise the boom and check for leaks and check for clearance.	the rear right wheel.
2.	Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.	ROB
3.	Cable tie the pressure sensor cables to the flexible hydraulic hoses connected to the compensation cylinder down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.  Run the cables towards the rear of the machine and cable tie with the	
	other cables during External Cable Completion on page 22.	View from under the boom behind the rear left wheel.

Table 6: Compensation Pressure Sensor Installation

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# **Can Pressure Input Module (CPIM)**

The CPIM is responsible for processing the information send from the pressure sensors.



Accidentally swapping the pressure sensor connections will not damage the system.



Do not plug the pressure sensor cable into the far right side boom cable. This will damage the system.

Step	Description	Diagram
1.	Drill two M8 holes for the CPIM bracket in the side of the chassis.  Mount using the supplied M8 x 30mm bolts, nuts and washers.	
2.	Connect the cables for the pressure sensors and boom cable to the CPIM according to the picture shown.  Note: The CCIM cable will be installed during External Cable Completion on page 22.	CCIM  CCIM  COMMITTED  COMMITTED

Table 7: Can Pressure Input Module (CPIM) Installation

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# **Signal Light Installation**

The signal light warns other workers when the telehandler is lifting loads close to it's maximum capacity.



Ensure the power supply voltage is greater than 13.5V otherwise the signal light may not illuminate correctly.

Step	Description	Diagram
1.	Mount the signal light to the top of the cabin using the magnetic anchor.	View from on top of the cabin
2.	Inside the cabin, remove the covers behind the seat leading to the joystick.	

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Step	Description	Diagram
3.	Cut the signal light cable approximately 300 mm from the end of the M12 connector.	
	Feed the cable through one of the existing grommets for the rotating beacon into the cabin.	
	Note: As an alternative to cutting the cable the grommet hole can be enlarged to fit the M12 connector.	
	Note: The signal light cable must be run through an existing grommet hole. Drilling another hole in the cabin will invalidate the ROPS/FOPS protection of the cabin.	
4.	Run the cable along the same path as the existing cables past the joystick to inside the dashboard and secure using cable ties.	
	Replace the dashboard covers.	
5.	Inside the cabin, reconnect the 4 wire cable using the supplied crimp joiners.	
	Secure the joined connections using electrical tape (not shown)	

Table 8: Signal Light Installation

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#### **Forward Camera**

The forward camera video is displayed on the screen when the machine is in forward gear to allow the operator to see past the boom to obstructions that would damage the right front tyre.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Mount the camera to the side mirror post using the p-clips as shown.  Secure using two M6 nuts.	BohGal
2.	Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032).  Note; The white connector is not used.	
	Run the cable along the same path as the headlight cable through the headlight post.  Run the remainder of the cable towards the cabin following the headlight cable and insert into cabin during External Cable Completion on page 22.	

Table 9: Forward Camera Installation

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The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



For further details on running the camera cable refer to the Installation Index on page 6

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# **External Cable Completion**

All external cabling is completed in this step.

Step	Description	Diagram
1.	Drill a 31mm hole into the side of the chassis near the existing connector entry points into the cabin.  Install the supplied grommet	View from front right of machine to cabin
2.	Run the two pin connector pairs from the cutout and lock pin release harnesses through the connector hole from inside the cabin to the outside of the chassis.	
3.	Connect the supplied M12 4 metre cable (CB001026) into the right side of the CPIM for the CCIM cable.	CCIM  CCIM

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Step	Description	Diagram
4.	Run the cutout and lock pin release harnesses along the same path under the chassis covers as the existing electrical harnesses towards the spool assembly at the rear of the machine.  Run the CCIM cable along the same path as the existing electrical harnesses towards and through the hole into the cabin.	
5.	Run the two pin connectors on the lock pin release harness up to the lock pin release solenoid valve and secure in place using cable ties.  This will be connected into the solenoid valve during Finalisation on page 36.	View from under the boom towards the rear of the machine
6.	Run the pair of two pin connectors on the height limit cable from out the side of the CPIM module and the two pin connectors from the cutout harness to the spool assembly.	View from under the boom towards the rear of the machine

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Step	Description	Diagram
7.	Connect into the spool assembly as shown and secure in place using cable ties.  Once secure remove the connections so that the boom will function.  These will be reconnected into the proportional valves during Finalisation on page 36.	Extend Raise Lower
8.	Coil up the additional cabling for the pressure sensor, CCIM and boom cables and store underneath the CPIM.	View from behind the cabin
9.	At the front of the machine run and cable tie the forward camera towards the cabin.	

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Step	Description	Diagram
10.	Drill a 31mm hole into the cabin in the location shown next to the existing connector cabin entry point and insert the supplied grommet.	View from front right of machine to cabin
11.	Run the CCIM, signal light and forward camera cables up through the hole into the cabin.  Note: Pull a short length of cable through into the cabin. Store excess cable under the cover on the side of the chassis.	View from front right of machine to cabin

Table 10: External Cable Completion

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# **Display Installation**

The display shows the current safety status of the telehandler.

Step	Description	Diagram
1.	Remove the rear mirror from the right column.	
	Use the existing bolts to mount the display adaptor bracket to the rear mirror mount.	

Table 11: Display Installation



Adjust the display bracket for optimal viewing angle once the display is powered



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 45 for the correct method of attaching to the display connectors.

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#### **User Control**

The user control consists of a single dial switch mounted in the dashboard.

Step	Description	Diagram
1.	Drill a 39 mm hole into the dashboard below the switch panel as shown.  Install the user control dial in the dashboard, aligned so the Enter cap is facing up.	

Table 12: User Control Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 45 for the correct method of attaching to the display connectors.

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# Can Cabin Interface Module (CCIM)

The CCIM connects the system into the machine electronics.

Step	Description	Diagram
1.	Position the CCIM on the plate above the steering column under the dashboard using double sided velcro tape.	
	Position the backup battery next to the CCIM using double sided velcro tape.	
	Remove the battery and CCIM from the velcro to allow the connections to be completed. Reattach to the velcro in the section Finalisation on page 36.	View from the from the floor of the cabin towards the steering column

Table 13: CCIM Installation

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#### **Machine Connections**

The following procedures connect the safety systems to the existing electronics in the machine.



Isolate the main battery before starting the machine connections



After completing the machine connections the boom can not be moved until the installation is complete

Step	Description	Diagram
1.	Remove the plate holding the joystick.  Connect the 6 pin tee connectors from the CAN I/O module harness into the joystick connector C256.	
2.	Secure the CAN I/O module to the side of the cabin chassis using velcro tape.	View through the joystick mounting hole

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Step	Description	Diagram
3.	Locate connector C234 in the set of connectors on the harness running to the steering wheel switches under the dashboard panel.	
4.	Cut the blue wire #3310 and join the violet wire from the CAN I/O module to the wire running to the steering wheel switches.  Join the other side of the wire to the yellow wire from the CAN I/O module.  Secure the wire joins with electrical tape.	View behind the dashboard
5.	Locate the ignition key switch terminal C210 in the removable dashboard panel.  Connect the 6 pin tee connection on the power harness into the C210 connector.	View behind dashboard panel

Step	Description	Diagram
6.	Locate the ground lug near the bulkhead connectors attached to the side of the chassis.  Attach the ring lug from the power harness to the ground lug.	View from the from the floor of the cabin towards the middle of the machine

Table 14: Machine Connections

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### **Cabin Loom**

The cabin loom connects the CCIM to the machine connections and the other modules of the system.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Connect the CCIM and signal light cables to the M12 connectors on the CCIM.  Note: It doesn't which of the M12	Canara / Power 100 CAN
	connectors the CCIM and signal light cables are plugged into.	
2.	Connect the power/camera and IO harnesses to the CCIM bulk head connectors	CKUD-Battery CC
3.	Connect the forward camera cable to the power/camera harness.  Note; The rear camera connections are not used and the white connector is not used.	

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Step	Description	Diagram
4.	Connect the 4 pin connector from the machine input harness into the IO harness.	
	Connect the 6 pin connector from the machine cutout harness to the IO harness.	
	Connect the 12 pin connector from the lock pin release harness to the IO harness.	
	Note: The 2 pin connection on the IO harness is not used.	
5.	Run the 8 pin CCIM cable and the 5 pin user control cable through the gap in the dashboard for the existing display.	
	Note: The clip-on ferrites will need to be removed to run the cables through the gap between the window and the dashboard. Reattach the ferrites according to Appendix A: Attaching Display Connectors on page 45.	

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Step	Description	Diagram
6.	Run the cables through snake tube.  Cable tie to the tube running to the LMI.  Connect into the 8 pin and 5 pin connectors into the display	
7.	Connect the spade lug on the black wire to the negative (black) battery terminal on the backup battery.  Connect the spade lug on the blue wire to the positive (red) battery terminal on the backup battery.	

Table 15: Cabin Loom Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 45 for the correct method of attaching to the display connectors.

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If the clip-on ferrites were removed from the CCIM and user control cables. See Appendix B: Reattach Ferrites and page 49 for the correct reattachment position.

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## **Finalisation**

This section will complete the final power connections to power the system and finish any additional items.

Step	Description	Diagram
1.	Connect the 3 pin connector from the power harness into the power/camera harness.  Coil up and store the wire harnesses under the dashboard.	GO 36  13 29 30 30 30 30 30 30 30 30 30 30 30 30 30
2.	Attach the backup battery to the velcro on the CCIM and attach the CCIM to the velcro installed earlier to the cabin chassis	View from the from the floor of the cabin towards the steering column

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Step	Description	Diagram
3.	Reconnect the tee connectors back into the spool assembly and the lock pin release solenoids.	View from under the cylinder towards the proportional valve connections
4.	Turn the machine onto first stage /accessories and ensure the system is activated.  Adjust the display bracket for optimal viewing	
	Place the machine in forward gear to active the forward camera. Adjust the forward camera so the front right wheel is visible.	

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Step	Description	Diagram
5.	Operate the boom movement controls to test if a false N07 fault occurs.	
	If a N07 fault does occur, adjust the arm on the stow switch forwards towards the stow switch trigger.	
	Note: The actual switch arm orientation may differ from the picture.	
6.	Perform a final check on all the cabling and sensors.	MIM.
	Replace all the covers	

Table 16: Finalisation



Complete the system checklist once installation has been completed.

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#### **Set Time & Sensor Calibration**

Once the installation is complete, the time will need to be set and the sensors will require calibration.



A sensor calibration must be performed once the cable reeler and CPIM have been mounted. If the cable reeler or CPIM have been moved/repositioned a recalibration must be performed

Step	Description	Diagram
1.	Press Enter on the user control dial	Main Menu
	to enter the menu system.  Press the arrow buttons to select	Attachment Selection Menu
	System Menu.	
	Press Enter to select the menu.	System Menu
		Exit Menu
2.	Select Advanced Menu	System Menu
		Volume / Brightness
		Status Menu
		Diagnostics Menu
		System Tests
		Advanced Menu
		Return to Main Menu

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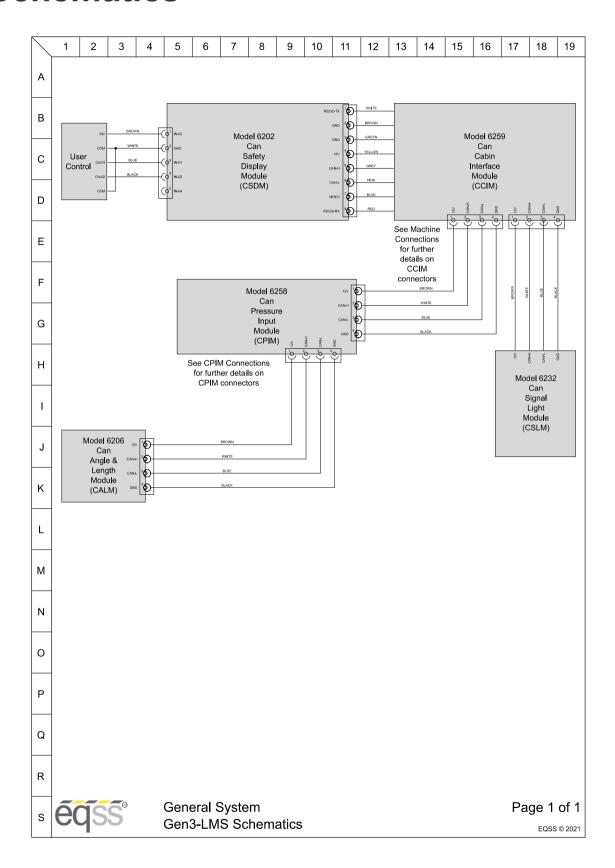
Step	Description	Diagram
3.	Enter the password	Enter Password
	(Default Password: 2-8-4)	Number 1 2
		Number 2 8
		Number 3 4
		Submit Password
		Return to System Menu
4.	Select Set Time / Date	Advanced Settings
1.	Lesses des Time, 2 des	Set Time / Date
		Sensor Calibrations
		Change Language
		Change Password
		Return to System Menu
5.	Enter the correct time and date for	Set Time / Date
0.	your area.	Hour 15
	Press the arrow keys to select a	Minute 54
	time/date parameter	Day 10
	Press Enter and the parameter will	Month 2
	to change the value and then press the Enter key to store the value.	Year 2016
		Region Melbourne
	Note: The hour parameter is in 24 hour clock	
	Repeat for the rest of the time values	

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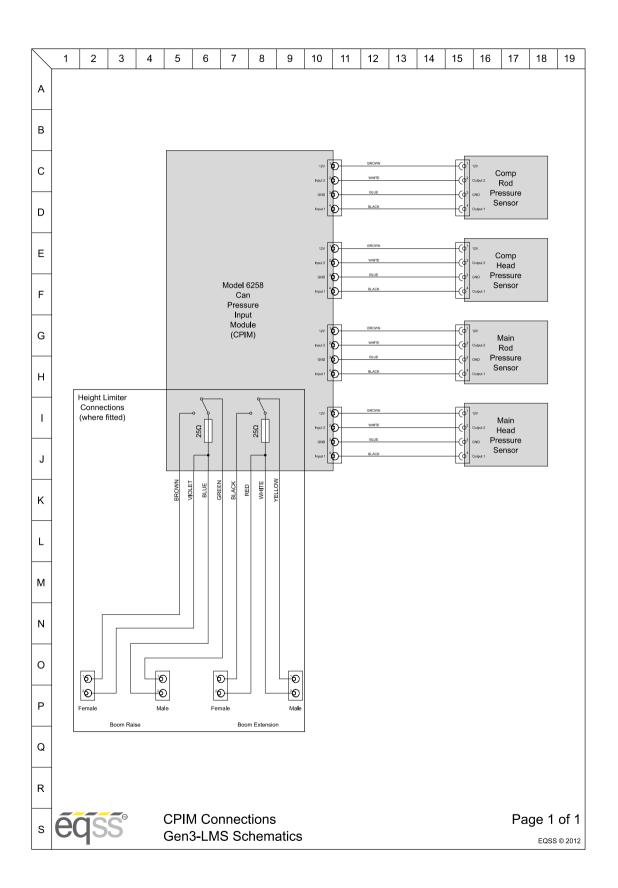
Step	Description	Diagram
6.	Scroll to the next page and select	Save
	6. Scroll to the next page and select Save to store the new time/date and return to the Advanced Menu.  7. Select Sensor Calibrations  8. Select Calibrate Carrier Angle and then follow the instructions on the screen to complete the calibration.	
		Return to Advanced Menu
		Advanced Settings
1.	Select Sensor Calibrations	Set Time / Date
		Sensor Calibrations
		Change Language
		Change Password
		Return to System Menu
8	Select Calibrate Carrier Angle and	Sensor Calibration Menu
<b>.</b>	then follow the instructions on the	Calibrate Carrier Angle
	screen to complete the calibration.	Calibrate Boom Angle
	Repeat for Calibrate Boom Angle and Calibrate Boom Length.	Calibrate Boom Length
		Return to Advanced Menu

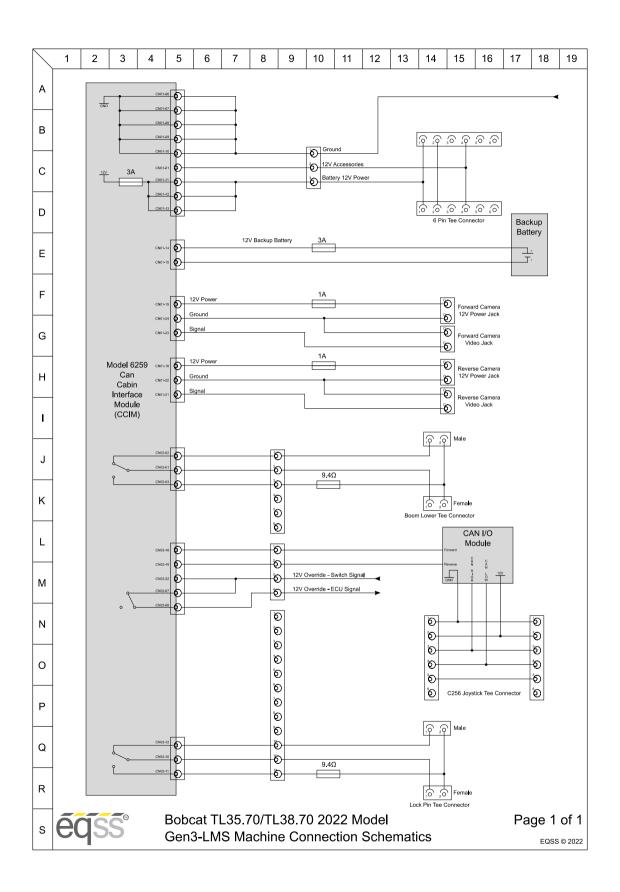
Table 17: Sensor Calibration

### **Schematics**



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# **Appendix A: Attaching Display Connectors**

The procedure below describes the correct method of attaching the cables to the screw lock connectors on the display.



If the M12 screw lock connectors on the display are over tightened, it will twist the connector pins attaching the connector to the PCB.

Step	Description	Diagram
1.	Connect the cable from the user control to the top 5 pin connector on the display.  Connect the cable from the CCIM to the bottom 8 pin connector on the display.	9 5 Pin - User Control
2.	Line up the alignment hole on the cable connector with the alignment notch on the display connector.	

Step	Description	Diagram
3.	Push the female connector from the cable into the male connector on the display.	
4.	Rotate the nut on the female connector by hand in a clockwise direction, until the tension on the nut starts to increase.	
5.	Push the cable in again and repeat steps 3 and 4 until the connector is secure.	

Table 18: Install Display Connector Procedure



The method to correctly secure the cable is to push-twist-push-twist until the connector is fully inserted and secure. This will minimise the twisting force applied to the connector.

Below is a picture of a damaged connector on the PCB inside the display. This damaged occurred because the connector was over tightened.

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Illustration 4: Damaged Display Connector



Do not use any tools to tighten the connector.



Illustration 5: Do Not Use Tools To Tighten Connector

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Do not over-tighten the nuts on the back of the display connectors. These nuts should only be hand tightened. If the nuts are overtightened it will damage the PCB inside the display.



Illustration 6: Do Not Over Tighten Nuts



Damage to the display connectors is not covered under warranty.

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# **Appendix B: Reattach Ferrites**

If the clip-on ferrites on the displays are removed during installation, they will need to be reattached as shown in the procedure below.



If the ferrites are not reinstalled or attached in the specified location the Gen3-LMS kit will not meet the AS/NZS CISPR 22:2006 certification.

Step	Description	Diagram
1.	Attach the two clip-on ferrites at a location of 60 mm and 260 mm from the start of the connector to the start of the ferrite.  Do this for both the CCIM and user control cables that plug into the display.	

Table 19: Reattach Ferrites Procedure

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