

eqss™ Gen-3 LMS Telehandler Load Management System

Installation Manual for Privilege MT1840 A / EP Manual Tool Recognition



PLEASE NOTE:

Do Not Swap Components between Gen3-LMS kits
When installing multiple Gen3-LMS kits, make sure the serial number on the sticker matches the serial number on the machine.

Failure To Follow Installation Manual Will Void Warranty

Documentation Conventions

The list below highlights important documentation conventions.



Text presented in this manner is intended to provide the user with some general information. The user should ensure information presented in this manner is clearly understood.



Text presented in this manner provides the user with information to assist in completion of the current procedure being explained.



Text presented in this manner indicates that a failure to follow directions could result in damage to equipment, loss of information, bodily harm, or loss of life.

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Important Information

Information contained in this publication regarding this device's applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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Tools Required for Installation

The tools required to perform the installation of the TSS are listed below

- Pencil or Texta
- Drill
- Drill bits
 - 。 3.3 mm
 - 4.5 mm
 - 。 5 mm
 - 6.25 mm
 - 6.8 mm
 - 。 8.5 mm
- Centre punch
- Tap T-Handle
- Taps
 - M6
 - o M7 x 0.75
 - 。 M8
- Drill and tap oil
- Metric Allen keys
- · Phillips Head screw driver
- Spanners and sockets
 - 7 mm
 - 10 mm
 - 13 mm
- · Locktite thread locker
- Side cutters
- Stanely knife
- Crimpers
- · Wire strippers

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Installation Index

The components and cables of the Gen-3 Telehandler Load Management System are outline in the tables below. The following pages show where the components are installed and the cable routing.

See the appropriate manual section for a detailed installation description for each component.



Refer to this section for any component placement or cable routing issues

Item	Component Description
1	Cable Reeler
2	Main Lift Cylinder Pressure Sensors
3	Compensation Cylinder Pressure Sensors
4	Can Pressure Input Module (CPIM)
5	Forward Camera
6	Signal Light
7	Rear Camera
8	Can Cabin Interface Module (CCIM)
9	Display Module
10	User Control Dial
11	Stabiliser Connections
12	Joystick X67
13	Cutout
14	Cabin Fuse Box

Table 1: Component Installation Index

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Colour	Cable Description	
Yellow	Boom Cable	
Dark Green	Main Cylinder Pressure Sensor Cables	
Dark Blue	Compensation Cylinder Pressure Sensors Cables	
Light Blue	Forward Camera Cable	
Violet	Signal Light Cable	
Aqua	Rear Camera Cable	
Dark Purple	CCIM Cable	
Yellow/Green	Cutout Cable Harness	
Brown	Joystick Cable Harness	
Dark Yellow	Stabiliser Harness	
Red	Display Cable	
Orange	User Input Control Cable	

Table 2: Cable Installation Index



Illustration 1: Machine Boom

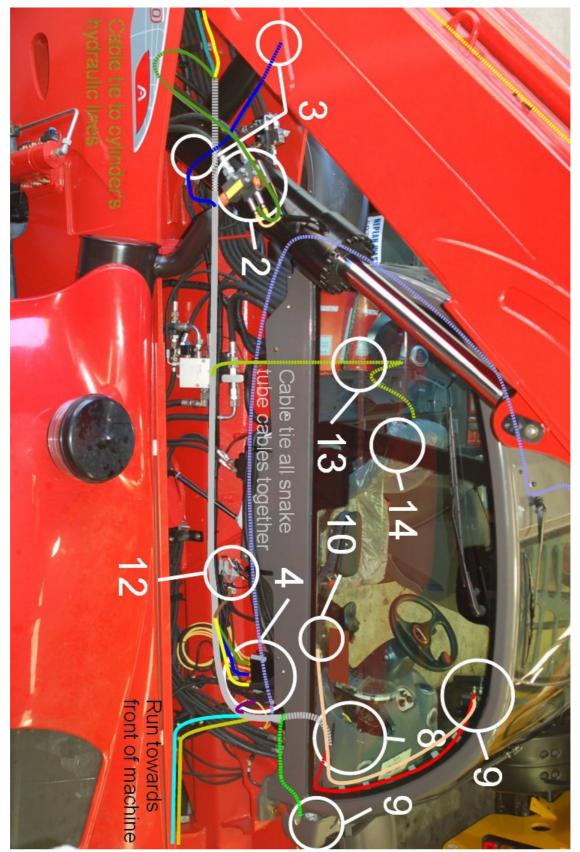


Illustration 2: Machine Chassis

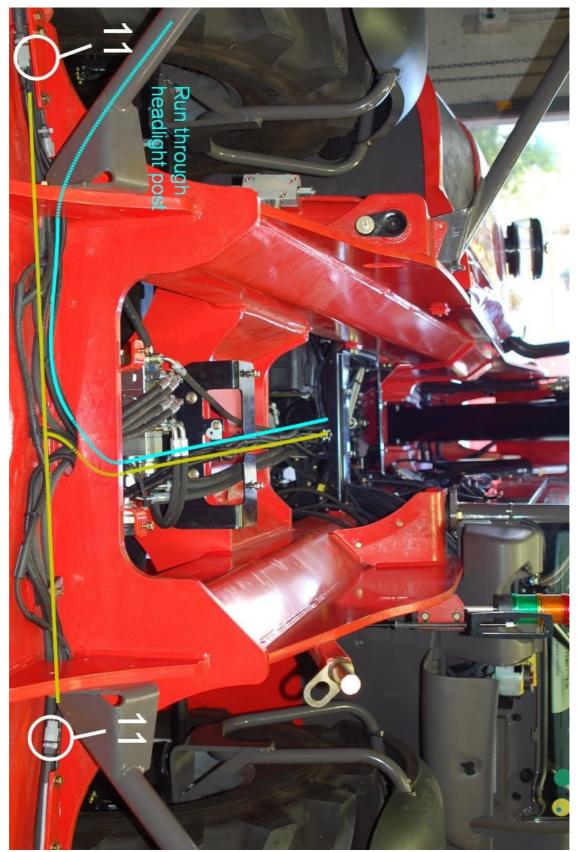


Illustration 3: Front of Machine

Covers

Remove the following covers before starting the installation

Step	Description	Diagram
1.	Remove the top rear cover behind the boom.	
2.	Remove the side panel next to the cabin under the boom.	
3.	Remove the covers under the boom. Remove the covers over the stabiliser connections	

Step	Description	Diagram
4.	Remove the cover behind the cabin	
5.	Inside the cabin remove the dashboard display. Remove the fuse box cover.	

Table 3: Cover removal

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Cable Reeler Installation

The cable reeler is used to measure the boom extension to determine the maximum lifting capacity.



A false N07 fault can occur if the boom jumps off the stow switch due to pressurising the hydraulic system and without operating the boom extension control. Ensure the stow switch arm is correctly adjusted to prevent this error.



When mounting the cable anchor ensure it is mounted on the first extendable section not on the last section. If mounted on the last section the cable reeler will be damaged when the boom is extended.

Step	Description	Diagram
1.	Drill and tap the holes for the cable reeler according to the mounting diagram on page 17.	
	Mount using the supplied M6 x 16 mm bolts and washers.	
2.	Drill and tap an M8 hole for the cable anchor. Ensure the cable anchor is positioned so the cable runs in line with the boom.	
	Mount the cable anchor and attach the cable.	
	Note: Ensure the anchor is mounted on the first extendable section not on the last section. If mounted on the last section the cable reeler will be damaged when the boom is extended.	

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Step	Description	Diagram
3.	Drill and tap the M6 holes for the stow switch trigger bracket. Mount the stow switch trigger bracket using the supplied M6 x 12 mm bolts and washers. Adjust the length of the trigger plate to ensure the stow switch is pressed when the boom is retracted.	
4.	Connect the supplied M12 10 metre cable (CB001027) into the cable reeler connection.	
5.	Run the cable along the hydraulic pipes running down the boom, secure using cable ties every 150 mm to 200 mm. Cable tie to the flexible hydraulic hoses down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	
	Run the remainder of the cable towards the cabin and insert into snake tube with the reverse camera cable during External Cable Completion on page 33.	

Table 4: Cable Reeler Installation

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For further details on running the boom cable refer to the Installation Index on page 7

Cable Reeler Mounting Position

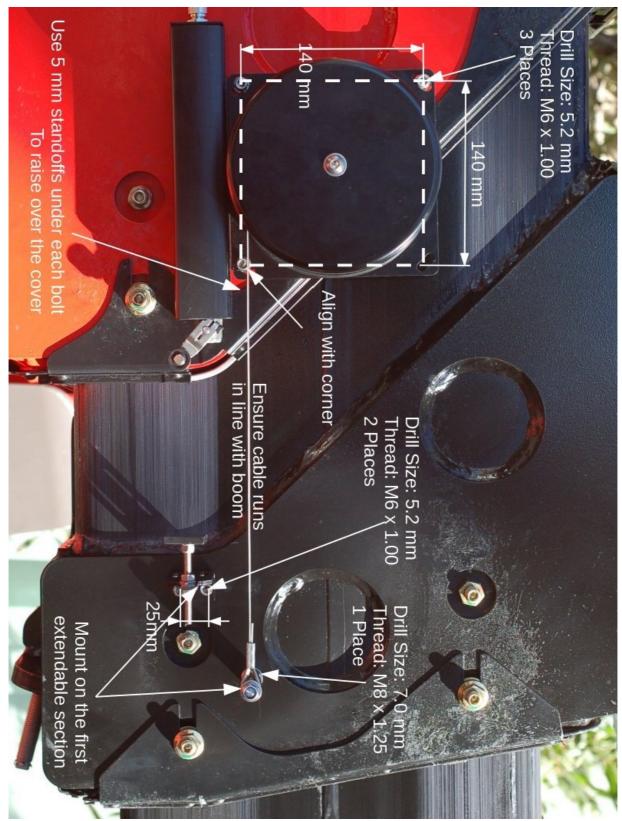


Illustration 4: Cable Reeler Mounting Position

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Pressure Sensor Installation

The hydraulic pressure sensors are used to measure the lifting load of the telehandler.

Pressure Manifold



Failure to tighten the bolts to the correct torque on the pressure manifold may result in a pressure failure on the counterbalance valve causing an uncontrolled fall of the boom.

Step	Description	Diagram
1.	Raise the boom to approximately 40 degrees.	M Rod
	Support and secure the boom using an A Frame or similar apparatus. It must support at least 2 tons.	M Head
	Apply the handbrake and insert chock under wheels.	
	Remove the counterbalance valve on the side of the hydraulic lifting ram.	
	Removing the counterbalance valve will release the hydraulic pressure which may result in a spray of oil.	
	Secure the pressure manifold using the supplied 70 mm bolts and seals. Tighten the bolts for the manifold to 25 NM using a torque wrench.	
	Start the machine, pressurise the boom and check for leaks.	

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Step	Description	Diagram
2.	Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.	
	Add both cables to 3 m of snake tube. Cable tie to the flexible hydraulic hoses connected to the main lift cylinder. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.	
	Run the snake tube and cables towards the cabin and cable tie with the other cables during External Cable Completion on page 33.	

Table 5: Pressure Manifold Installation



For further details on running the pressure sensor cables refer to the Installation Index on page 7

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Compensation Pressure Sensors

	Compensation Flessure Sensors		
Step	Description	Diagram	
1.	Install the pressure sensor with the U shaped hydraulic connection into the rod of the compensation cylinder	View from behind the cabin towards the rear of the machine	
2.	Install the head compensation pressure sensor into the compensation cylinder Start the machine, pressurise the boom and check for leaks. Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors. Add both cables to 3 m of snake tube. Run the snake tube and cables towards the cabin and cable tie with the other cables during External Cable Completion on page 33.	View from under the boom towards the rear of the machine	

Table 6: Compensation Pressure Sensor Installation



For further details on running the pressure sensor cables refer to the Installation Index on page 7

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Reverse Camera

The rear camera video is displayed on the screen when the machine is in reverse gear to allow the operator to see behind the telehandler while reversing.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Remove the cover at the rear of the machine. Drill a 31mm hole in the location shown. Making sure to leave enough room for a license plate Insert the camera through the hole and adjust the angle using the alignment washers.	MANITUU
2.	Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032). Note; The white connector is not used. Secure the camera cable using a single cable tie to maintain the connector location.	
	Run the remainder of the cable towards the cabin and insert into snake tube with the boom cable during External Cable Completion on page 33.	

Table 7: Reverse Camera Installation

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The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



Once the cable has secured with a cable tie disconnect the cable to remove the rear cover until the installation is finalised



For further details on running the camera cable refer to the Installation Index on page 7

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Cutout Cable Harness



Isolate the main battery before connecting into the machine wiring

Step	Description	Diagram
1.	Remove connector X148 from the ECU MP1.	
2.	Pull the connector on the left of the connector to disconnect from the ECU. Slide the protective cover off the end of the connector to access the wires.	
3.	Remove the pin support bracket from the left connector, by levering the corners with a small screwdriver.	

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Step	Description	Diagram
4.	Remove the blanking pin from the connector in slot 4 and insert the blue wire from the cutout harness. Note: The pin numbers are written on the front of the connector	
5.	Replace the pin support bracket and the protective cover. Replace any tape that was removed to secure the snake tube of the protective cover. Reattach the connector to the ECU module.	ACTIA III MANIMAN PROPRIA PLA TO THAT WAS ALLOW AND ALLO
6.	Push the snake tube containing the green wire through the seal into the fuse box up to the start of the snake tube. Cable tie the snake tube into the existing tube going into the seal.	
7.	Run the cable from behind the cabin to the side of the chassis following the existing snake tube.	

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Step	Description	Diagram
8.	Run the snake tube and cables towards the cabin and cable tie with the other cables during External Cable Completion on page 33.	

Table 8: Cutout Cable Harness Installation



For further details on running the cutout cable harness refer to the Installation Index on page 7

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Forward Camera

The forward camera video is displayed on the screen when the machine is in forward gear to allow the operator to see past the boom to obstructions that would damage the right front tyre.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Drill two 7 mm holes spaced 25 mm apart on the top of the right headlight to mount the camera. Mount the camera to the top of the headlight and secure using the supplied nuts.	
2.	Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032). Note; The white connector is not used. Run the cable along the same path as the headlight cable through the headlight post. Run the remainder of the cable towards the cabin and cable tie with the stabiliser cable harness during External Cable Completion on page 33.	

Table 9: Forward Camera Installation

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The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



For further details on running the camera cable refer to the Installation Index on page $7\,$

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Stabiliser Cable Harness



Isolate the main battery before connecting into the machine wiring

Step	Description	Diagram
1.	Locate the stabiliser down pressure switch connections at the front of the machine. Connect the 3 pin tee connector	
	labelled left stabiliser into X97 and the connector labelled right stabiliser into X87 on the stabiliser cable harness.	X87
2.	Cable tie to the existing snake tube. Run the remainder of the cable towards the cabin and cable tie with the front camera cable harness during External Cable Completion on page 33.	

Table 10: Stabiliser Cable Harness Installation



For further details on running the stabiliser cable harness refer to the Installation Index on page 7

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Signal Light Installation

The signal light warns other workers when the telehandler is lifting loads close to it's maximum capacity.



Ensure the power supply voltage is greater than 13.5V otherwise the signal light may not illuminate correctly.

Step	Description	Diagram
1.	Mount the signal light on the top of the roof past the roof window towards the cabin door.	
2.	Run the cable towards the boom side of the roof and push through the hole near the window wiper. Note: It might be necessary to cut a hole in the plastic roof cover to fit the cable. Run the cable under the cover towards the rear corner.	

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Step	Description	Diagram
3.	Run the cable along the pipes under the cover towards the chassis. Cable tie with the other cables during External Cable Completion on page 33.	

Table 11: Signal Light Installation

Machine Input Harness



Isolate the main battery before connecting into the machine wiring

Step	Description	Diagram
1.	Locate the bundle of connectors under the boom next to the cabin, that connect into the joystick.	
	Connect the 12 pin tee connector into X67.	
	Run the other end of the cable with the 4 pin connector towards the cabin and cable tie with the other cables during External Cable Completion on page 33.	
	Note: The violet and yellow wires near the 4 pin connector are not used.	

Table 12: Joystick Cable Harness Installation



For further details on running the joystick cable harness refer to the Installation Index on page 7

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Can Pressure Input Module (CPIM)

The CPIM is responsible for processing the information sent from the pressure sensors.



Accidentally swapping the pressure sensor connections will not damage system and can be determined if the display is showing a negative load.



Do not plug the pressure sensor cable into the far right side boom cable. This will damage the system.

Step	Description	Diagram
1.	Drill and tap two M8 holes for the CPIM bracket in the cab side panel. Mount using the supplied M8 x 12mm bolts and washers.	
2.	Connect the cables for the pressure sensors and boom cable to the CPIM according to the picture shown. Note: The CCIM cable will be installed during External Cable Completion on page 33.	Boom C Rod M Rod M Head

Table 13: Can Pressure Input Module (CPIM) Installation

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External Cable Completion

All external cabling is completed in this step.

Step	Description	Diagram
1.	Locate the reverse camera cable and the boom cable at the rear of the machine and run both cables through the supplied 2.5 m section of snake tube up to the CPIM.	View from under the boom towards the rear of the machine
2.	At the front of the machine cable tie the stabiliser and front camera cables together up to the CPIM.	
3.	Cable tie the pressure sensor, boom, cutout cable harness, reverse camera, signal light and machine input harness together up to the CPIM. Coil up the additional cabling for the pressure sensor, boom and signal light cables and store underneath the CPIM.	

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Step	Description	Diagram
4.	Connect the supplied M12 4 metre cable (CB001026) into the free connection out of the right side of the CPIM for the CCIM cable.	Boom C Rod M Rod M Head
5.	Run the CCIM, cutout cable harness, stabiliser cable harness, signal light, machine input harness and camera cables up through the hole into the cabin under the dashboard.	
	Note: Pull the entire length of cable through into the cabin, excess cable will be stored under the dashboard cover in the cabin.	

Table 14: External Cable Completion

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Display Installation

The display shows the current safety status of the telehandler.

Step	Description	Diagram
1.	Attach the display bracket to the level indicator in the top right corner using the supplied M6 x 35 mm bolts and nuts. Attach the display to the bracket and	
	tighten the grub screw	

Table 15: Display Installation



Adjust the display bracket for optimal viewing angle once the display is powered



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 52 for the correct method of attaching to the display connectors.

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User Input Control

The user input control consists of a 5 button switch mounted in the dashboard.

Step	Description	Diagram
1.	Drill a 34 mm hole into the cover in front of the joystick and install the user control dial.	
	Note: Be careful while drilling not to damage the hydraulic controls positioned under the cover.	
2.	Run the cable through under the dashboard with the other cables.	

Table 16: User Input Control Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 52 for the correct method of attaching to the display connectors.

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Can Cabin Interface Module (CCIM)

The CCIM connects the system into the machine electronics.

Step	Description	Diagram
1.	Position the backup battery (to the right of the CCIM) underneath the dashboard using double sided velcro tape. Position the CCIM to the left of the backup battery using double sided velcro tape. Remove the battery and CCIM from the velcro to allow the connections to be completed. Reattach to the velcro in the section Finalisation on	
	page 42.	

Table 17: CCIM Installation

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Cabin Fuse Box Wiring

The following connections are located near the fuse box beside the seat in the cabin.



Isolate the main battery before connecting into the machine wiring

Step	Description	Diagram
1.	Locate the function selection switch (S52).	
	Insert the green wire from the cutout cable harness into the terminal with the existing green wires of the access mode switch block (the switch position shown).	
	Note: The switch block terminal may already be full, the green wire may need to be spliced into one of the existing green wires into the terminal.	

Table 18: Cabin Fuse Wiring Installation

Cabin Loom

The cabin loom connects the CCIM to the machine connections and the other modules of the system.



Isolate the main battery before connecting into the machine wiring



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

Step	Description	Diagram
1.	Connect the CCIM and signal light cables to the M12 connectors on the CCIM.	Copies 6259 CCIM Copies 6259 CCIM Copies 6259 CCIM Copies Copies 6259 CCIM Copies Copies Copies CCIM Copies Copies Copies CCIM Copies CC
	Note: It doesn't matter which of the M12 connectors the CCIM and signal light cables are plugged into.	Camera / Poser I.O. CAN
2.	Connect the Power/Camera and IO Harnesses to the bulkhead connectors on the CCIM.	

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Step	Description	Diagram
3.	Attach the ring lug from the cutout harness to the ground point underneath the dashboard.	
4.	Connect the camera power and signal cables to the cabin loom. Note: The white connector is not used.	
5.	Run the 8 pin cable from the CCIM and the 5 pin cable from the user control through the gap between the window and the dashboard.	

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Step	Description	Diagram
6.	Run the cables through snake tube.	
	Place cable tie points on the side of the window.	
	Cable tie the snake tube to the cable tie points.	
	Connect into the 8 pin and 5 pin connectors into the display	

Table 19: Cabin Loom Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 52 for the correct method of attaching to the display connectors.



If the clip-on ferrites were removed from the CCIM and user control cables. See Appendix B: Reattach Ferrites on page 56 for the correct reattachment position.

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Finalisation

This section will complete the final power connections to power the system and finish any additional items.

Step	Description	Diagram
1.	Connect the radio power harness into the radio power connector. Ensure there is a 2A fuse installed in F10 and a 7.5A fuse installed in F26 for radio power.	
2.	Connect the 12 pin, 6 pin, 4 pin, 3 pin and 2 pin connectors into the cabin loom.	
3.	Connect the spade lug on the black wire to the negative (black) battery terminal. Connect the spade lug on the blue wire to the positive (red) battery terminal.	

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Step	Description	Diagram
4.	Attach the backup battery and CCIM to the velcro strips installed earlier.	
5.	Coil up the extra cables and store underneath the dashboard cover.	
6.	Reconnect the main battery from the isolation switch. Turn the machine onto first stage /accessories and ensure the system is activated. Note: If the system is activated as soon as the battery power is reconnected, swap pins 2 and 3 on the 3 pin connector on the radio power harness.	

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Step	Description	Diagram
7.	Adjust the display bracket for optimal viewing Set the machine into forward gear to activate the forward camera. Adjust the forward camera so the front right wheel is visible. Set the machine into reverse gear to activate the reverse camera.	eass Gen Cuts
	Adjust the reverse camera so the video is level.	
8.	Operate the boom movement controls to test if a false N07 fault occurs. If a N07 fault does occur, adjust the arm on the stow switch forwards towards the stow switch trigger. Note: The actual switch arm orientation may differ from the picture.	
9.	Perform a final check on all the cabling and sensors. Replace all the covers	

Table 20: Finalisation



Make sure to update the machine ECU software for Australian configuration using the Manitou pad.



Complete the system checklist once installation has been completed.

Set Time & Sensor Calibration

Once the installation is complete, the time will need to be set and the sensors will require calibration.



A sensor calibration must be performed once the cable reeler and CPIM have been mounted. If the cable reeler or CPIM have been moved/repositioned a recalibration must be performed

Step	Description	Diagram
1.	Press Enter on the user control dial	Main Menu
	to enter the menu system.	Attachment Selection Menu
	Press the arrow buttons to select	
	System Menu.	System Menu
	Press Enter to select the menu.	
		Exit Menu
2.	Select Advanced Menu	System Menu
۵.	gereet riavaneed wiend	Volume / Brightness
		Status Menu
		Diagnostics Menu
		System Tests
		Advanced Menu
		Return to Main Menu

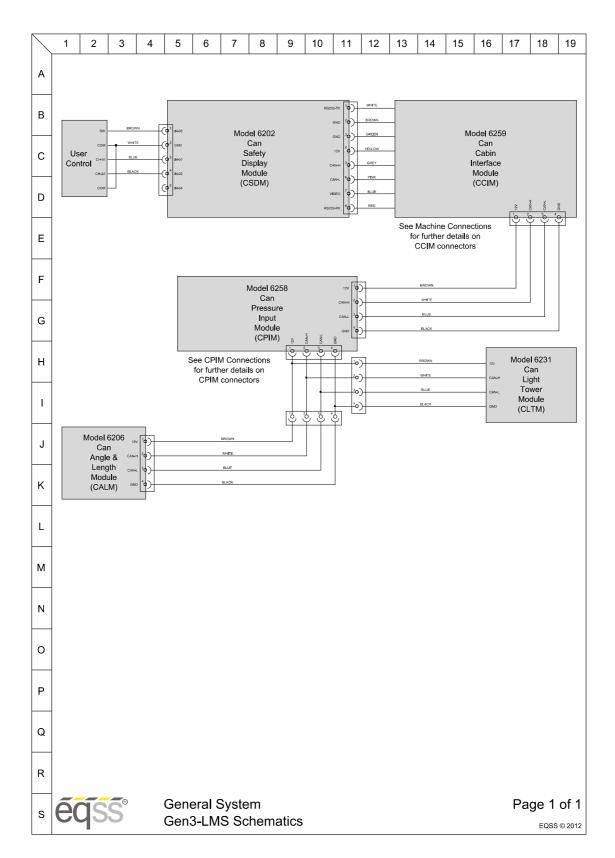
Step	Description	Diagram
3.	Enter the password (Default Password: 2-8-4)	Enter Password
.		Number 1 2
		Number 2 8
		Number 3 4
		Submit Password
		Return to System Menu
4.	Select Set Time / Date	Advanced Settings
4,	Sciect Set Time / Date	Set Time / Date
		Sensor Calibrations
		Change Language
		Change Password
		Return to System Menu
5.	Enter the correct time and date for	Set Time / Date
٠.	your area.	Hour 15
	Press the arrow keys to select a time/date parameter	Minute 54
		Day 10
	Press Enter and the parameter will	Month 2
	change to red, press the arrow keys to change the value and then press the Enter key to store the value.	Year 2016
		Region Melbourne
	Note: The hour parameter is in 24 hour clock	
	Repeat for the rest of the time values	

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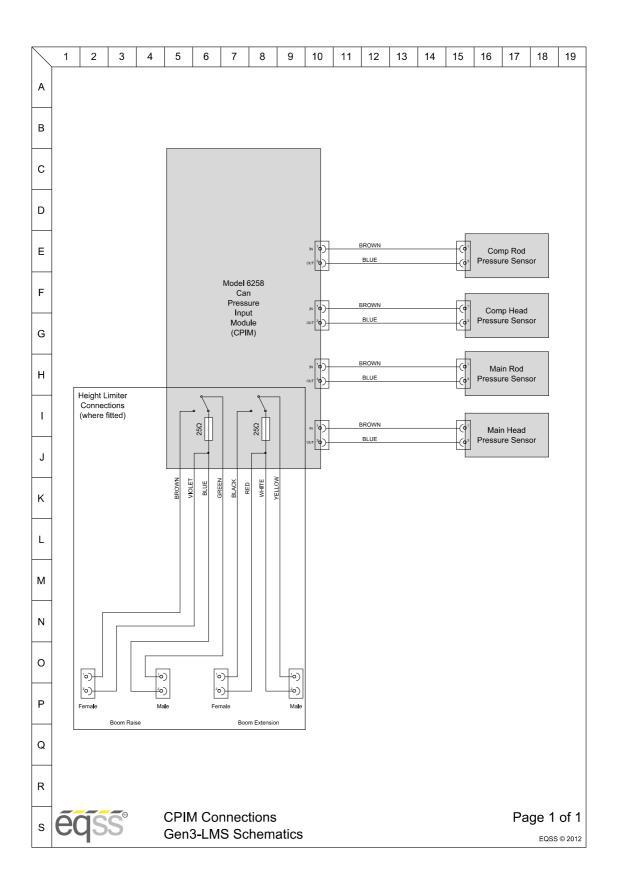
Step	Description	Diagram
6.	Scroll to the next page and select Save to store the new time/date and return to the Advanced Menu.	Save
		Return to Advanced Menu
7.	Select Sensor Calibrations	Advanced Settings
		Set Time / Date
		Sensor Calibrations
		Change Language
		Change Password
		Return to System Menu
8.	Select Calibrate Carrier Angle and then follow the instructions on the screen to complete the calibration.	Sensor Calibration Menu
		Calibrate Carrier Angle
		Calibrate Boom Angle
	Repeat for Calibrate Boom Angle and	Calibrate Boom Length
	Calibrate Boom Length.	Return to Advanced Menu

Table 21: Sensor Calibration

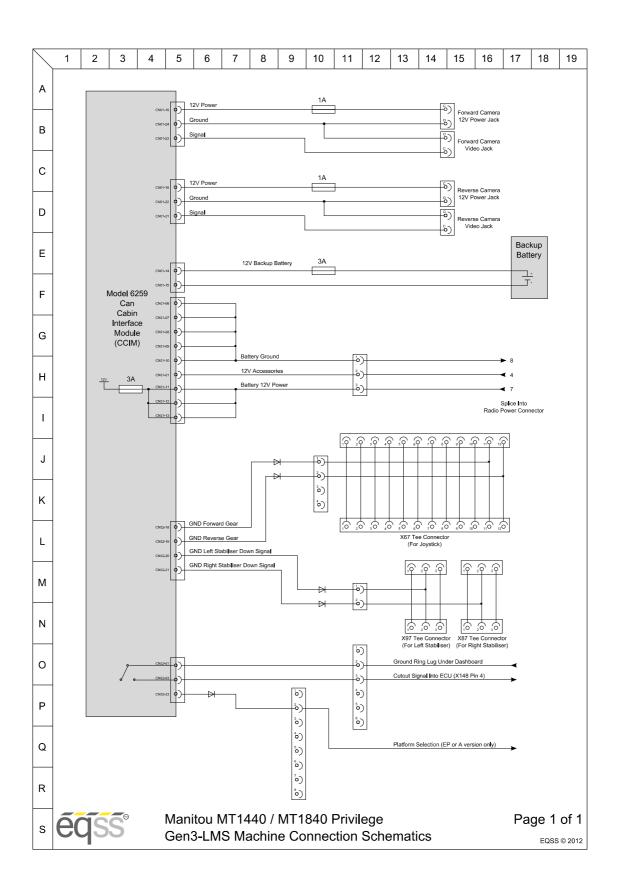
Schematics



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Appendix A: Attaching Display Connectors

The procedure below describes the correct method of attaching the cables to the screw lock connectors on the display.



If the M12 screw lock connectors on the display are over tightened, it will twist the connector pins attaching the connector to the PCB.

Step	Description	Diagram
1.	Connect the cable from the user control to the top 5 pin connector on the display. Connect the cable from the CCIM to the bottom 8 pin connector on the display.	9 5 Pin - User Control
2.	Line up the alignment hole on the cable connector with the alignment notch on the display connector.	

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Step	Description	Diagram
3.	Push the female connector from the cable into the male connector on the display.	
4.	Rotate the nut on the female connector by hand in a clockwise direction, until the tension on the nut starts to increase.	
5.	Push the cable in again and repeat steps 3 and 4 until the connector is secure.	

Table 22: Install Display Connector Procedure



The method to correctly secure the cable is to push-twist-push-twist until the connector is fully inserted and secure. This will minimise the twisting force applied to the connector.

Below is a picture of a damaged connector on the PCB inside the display. This damaged occurred because the connector was over tightened.

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Illustration 5: Damaged Display Connector



Do not use any tools to tighten the connector.



Illustration 6: Do Not Use Tools To Tighten Connector



Do not over-tighten the nuts on the back of the display connectors. These nuts should only be hand tightened. If the nuts are overtightened it will damage the PCB inside the display.



Illustration 7: Do Not Over Tighten Nuts



Damage to the display connectors is not covered under warranty.

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Appendix B: Reattach Ferrites

If the clip-on ferrites on the displays are removed during installation, they will need to be reattached as shown in the procedure below.



If the ferrites are not reinstalled or attached in the specified location the Gen3-LMS kit will not meet the AS/NZS CISPR 22:2006 certification.

Step	Description	Diagram
1.	Attach the two clip-on ferrites at a location of 60 mm and 260 mm from the start of the connector to the start of the ferrite. Do this for both the CCIM and user control cables that plug into the display.	

Table 23: Reattach Ferrites Procedure

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